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Reconciling float-based and tracer-based estimates of lateral diffusivities

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ABSTRACT

Lateral diffusivities are computed from synthetic particles and tracers advected by a velocity field derived from sea-surface height measurements from the South Pacific, in a region west of Drake Passage. Three different estimates are compared: (1) the tracer-based “effective diffusivity” of Nakamura (1996), (2) the growth of the second moment of a cloud of tracer and (3) the single- and two-particle Lagrangian diffusivities. The effective diffusivity measures the cross-stream component of eddy mixing, so this article focuses on the meridional diffusivities for the others, as the mean flow (the ACC) is zonally oriented in the region.

After an initial transient of a few weeks, the effective diffusivity agrees well with the meridional diffusivity estimated both from the tracer cloud and from the particles. This proves that particle- and tracer-based estimates of eddy diffusivities are equivalent, despite recent claims to the contrary. Convergence among the three estimates requires that the Lagrangian diffusivities be estimated using their asymptotic values, not their maximum values. The former are generally much lower than the latter in the presence of a mean flow.

Sampling the long-time asymptotic behavior of Lagrangian diffusivities requires very large numbers of floats in field campaigns. For example, it is shown that hundreds of floats would be necessary to estimate the vertical and horizontal variations in eddy diffusivity in a sector of the Pacific Southern Ocean.

1. Introduction

Quantifying tracer transport by geostrophic eddies is one of the outstanding problems in large-scale ocean dynamics. Geostrophic eddies set the rate at which tracers like heat and carbon are mixed laterally and vertically in the ocean and play a central role in determining large-scale circulation patterns, such as the meridional overturning circulation (see, e.g., the reviews by Olbers et al., 2004; Marshall and Speer, 2012).

The mixing induced by geostrophic eddies is often quantified in terms of an eddy diffusivity. The component of the diffusivity across the mean currents is most relevant, because

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tracer transport along currents is generally dominated by the current itself. The cross-current eddy diffusivity $K$ is defined as

$$\bar{v}C' = -K \bar{C}_y,$$

(1)

where $\bar{v}C'$ is the cross-current tracer flux and $\bar{C}_y$ is the cross-current tracer gradient.\(^4\) Overbars denote large-scale averages and primes are departures from those averages. As noted hereafter, there are discrepancies in the literature about both the magnitude and spatial patterns of $K$, and it is a goal of this paper to help resolve these discrepancies.

Estimates of $K$ can be obtained from Eulerian data, from tracer distributions and from Lagrangian (particle) data. Early attempts to estimate $K$ with Eulerian data relied on mooring time series of velocity $v$ and tracer $C$ (e.g., temperature) to construct $\bar{v}C'$ and its relationship to $\bar{C}_y$ (e.g., Bryden and Heath, 1985). However, the time series are often too short for significant results (Wunsch, 1999). In addition, the estimates are hampered by the presence of large, nondivergent eddy fluxes that do not contribute to mixing (Marshall and Shutts, 1981).

Another example of Eulerian estimates is the use of satellite measurements of sea-surface height (SSH) in conjunction with mixing length theory (Prandtl, 1925) to estimate diffusivities, as proposed by Holloway (1986) and Ferrari and Nikurashin (2010). This approach has the advantage that time series at fixed locations lend themselves well to the determination of mean and residual quantities. The weakness is that the eddy diffusivity can be determined up to undetermined constants that appear in the mixing length theory.

Tracer-based estimates can be made from hydrographic data. Armi and Stommel (1983) studied the oxygen distribution in the Eastern North Atlantic in the context of an advective-diffusive equation and inferred an eddy diffusivity of approximately 500 m\(^2\)s\(^{-1}\) at 800 m depth. Similarly, Ferrari (2005) and Zika \textit{et al.} (2010) used temperature and salinity observations in the same region to estimate diffusivities of O(1000 m\(^2\)s\(^{-1}\)) at the surface and O(100 m\(^2\)s\(^{-1}\)) below 1,500 m. Jenkins (1998) studied tritium and $^3$He distributions in the same ocean patch and estimated $K \sim 1,200$ m\(^2\)s\(^{-1}\) at a depth of 300 m.

Such estimates assume a steady state of advection and diffusion. The evolution of the eddy diffusivity can only be deduced with observations of a time-evolving tracer distribution, as in the North Atlantic Tracer Release Experiment (NATRE; Ledwell \textit{et al.}, 1998). The diffusivity can then be estimated from the dispersion of the patch. The NATRE release (of sulphur hexafluoride) yielded an estimate of $K \sim 1,000$ m\(^2\)s\(^{-1}\) at 300 m depth, consistent with the steady-state estimates of Jenkins (1998).

Lagrangian estimates on the other hand derive from the trajectories of freely drifting instruments, like surface drifters and subsurface floats (e.g., Davis, 1991; LaCasce, 2008). The diffusivity is proportional to the derivative of the mean square separation of the particles.

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4. In general one expects the tracer flux to have both a down gradient and a skew component, $\bar{v}C' = -K \bar{C}_y + K_{skew} \bar{C}_x$. Here we assume that the averaging is taken over a long sector of the current so that $\bar{C}_x \approx 0$ and the skew component can be ignored. In the simulations described below $\bar{C}_x$ is identically zero, because we impose periodic boundary conditions to the tracer advected in the numerical channel.
from their starting positions, as first proposed by Taylor (1921). Early diffusivity estimates from drifting buoys in the North Atlantic were made by Freeland et al. (1975), Colin de Verdiere (1983) and Krauss and Böning (1987). Colin de Verdiere (1983) obtained a meridional diffusivity of $K \sim 1,700 \text{ m}^2\text{s}^{-1}$ at the surface and Freeland et al. (1975) obtained $K \sim 700 \text{ m}^2\text{s}^{-1}$ at 1,500 m depth.

However, some subsequent estimates were much larger. Zhurbas and Oh (2004) obtained values in excess of $4,000 \text{ m}^2\text{s}^{-1}$ at the surface in the Western Atlantic, reaching values of $20,000 \text{ m}^2\text{s}^{-1}$ in the vicinity of the Gulf Stream. Lumpkin et al. (2002) and McClean et al. (2002) found comparable values.

Diffusivities have also been measured in the Southern Ocean, which is the focus of this paper, and here too the results vary. Eulerian-based estimates, from SSH, yield values of 2,000–4,000 m$^2$s$^{-1}$ in the Antarctic Circumpolar Current (ACC), with smaller values in the subtropical gyres to the north (Keffer and Holloway, 1988; Stammer, 1998). However the tracer-based estimates differ. Using a technique proposed by Nakamura (1996) (Section 2), Marshall et al. (2006) obtained values of $O(1,000 \text{ m}^2\text{s}^{-1})$ near the core of the ACC and larger values of $O(2,000 \text{ m}^2\text{s}^{-1})$ to the north. This method yields only the cross-stream component of the diffusivity and thus in principle does not suffer from “contamination” by the mean flow or by skew fluxes. Lower diffusivities in the ACC are consistent with the mean flow suppressing cross-stream mixing (e.g., Ferrari and Nikurashin, 2010). The ACC weakens with depth, suggesting the diffusivity should have a subsurface maximum (as the eddy field is intensified near the current). Abernathey et al. (2010) found this to be the case, using the tracer-based diagnostic.

Lagrangian estimates, in contrast, tend to be larger. Lumpkin and Pazos (2007) and Sallée et al. (2008) obtained values in the vicinity of the ACC of approximately $4,000 \text{ m}^2\text{s}^{-1}$, using surface drifters, with smaller values north and south of the jet. The exception was near the western boundary currents, where the diffusivities were large. Consistent with some earlier studies in the North Atlantic (e.g., Lumpkin et al., 2002, and references therein), Sallée et al. (2008) found that $K$ is correlated with the eddy kinetic energy; the largest values were near the ACC, where eddy variability is most pronounced. However, not all the Lagrangian estimates agree. Using synthetic float data from a numerical model, Griesel et al. (2010) found much smaller cross-stream diffusivities, $O(750 \text{ m}^2\text{s}^{-1})$, in the polar frontal zone, consistent with the tracer-derived estimates. However, they did not observe a suppression of eddy mixing in the ACC itself, nor did their diffusivities exhibit a subsurface maximum.

Thus there are discrepancies among the estimates particularly in the Southern Ocean. This is a significant challenge for ocean and climate simulations, because coarse-resolution models are sensitive to the magnitude and the lateral and vertical structures of eddy diffusivities in the Southern Ocean (Griffies et al., 2005; Danabasoglu and Marshall, 2007). Indeed, ocean models can reproduce reasonable stratification and transports with meridional eddy diffusivities in the range of a few hundred to one thousand m$^2$s$^{-1}$ (e.g., Griffies et al., 2005). As such, it is important to understand why the tracer, Eulerian and Lagrangian diffusivity estimates differ.
Several studies have addressed this question previously. Sundermeyer and Price (1998) used an idealized ocean model to reproduce eddy statistics from the NATRE field campaign described above and simulated the motion of synthetic floats and tracers. Their Lagrangian estimates of $K$ were two to six times larger than the tracer-based estimates. Riha and Eden (2011) used an idealized zonally periodic channel with eddy-driven zonal jets to compare Lagrangian and Eulerian diffusivity estimates. Interestingly, their estimates were comparable, with the Lagrangian ones being slightly smaller. Incidentally, both methods indicated an increase of the eddy diffusivities with depth.

In the present work, we examine further the relationship between different diffusivity estimates. To this end, we use a three-dimensional velocity field representative of the Southern Ocean, derived from satellite measurements of SSH, to estimate eddy diffusivities from tracers and floats. We focus on a region in the Southern Ocean upstream from Drake passage, which is the site of a large field experiment, the Diapycnal and Isopycnal Mixing Experiment in the Southern Ocean (DIMES). A major goal of DIMES is to infer eddy diffusivities from tracer and float releases. Here we focus on diffusivity estimates; in a companion paper (Klocker et al., 2012), we examine mixing suppression by the mean flow.

The results suggest that cross-stream estimates of eddy diffusivities from both Lagrangian statistics and tracer releases converge if measured properly and if the statistics are adequate. The comparison is hindered by the mean flow, which causes the Lagrangian diffusivity to overshoot its asymptotic value. Correct estimates thus require integrating past this overshoot.

The paper is organized as follows: Section 2 examines the different methods for calculating the diffusivity and how they are related; Section 3 describes how we construct the velocity field used to advect tracers and floats; and Section 4 presents and compares the diffusivity estimates for a sector of the Southern Ocean upstream of Drake Passage. Section 5 then uses these results to discuss the implications for observational estimates of eddy diffusivities. The results are discussed in Section 6.

2. Theory

Here we compare theoretical estimates of tracer-based and particle-based diffusivities. The former is described by Nakamura (1996), Shuckburgh and Haynes (2003) and Marshall et al. (2006). The term derives from the advection-diffusion equation for a passive tracer, $C(x, y, t)$:

$$\frac{\partial}{\partial t} C + \nabla \cdot (u C) = \nabla \cdot (\kappa \nabla C),$$

(2)

where $u$ is taken to be a two-dimensional (horizontal) velocity, assumed nondivergent, and $\kappa$ is a small-scale diffusivity. The latter might be the molecular diffusivity or a numerical diffusivity imposed to make solutions stable. The equation can be written as a simple diffusion equation when expressed in coordinates defined by the tracer isolines

$$\frac{\partial}{\partial t} C = \frac{\partial}{\partial A} \left( K_{nak} \frac{\partial C}{\partial A} \right),$$

(3)
where $A$ is the area bounded by an isoline of the tracer $C$, assumed to be a monotonic function of $C$. Further,

$$K_{nak} = \frac{\kappa}{(\partial C/\partial A)^2} \frac{\partial}{\partial A} \int \int |\nabla C|^2 \, dA$$

(4)

is Nakamura’s effective diffusivity. This is proportional to the small-scale diffusivity, $\kappa$, but it also depends on the gradient of $C$, integrated over the area bounded by the isoline. Thus if stirring acts to increase the gradients, the effective diffusivity can be much larger than the small-scale value. Note that $K_{nak}$ has units of (length)$^2$/time, in contrast to a usual diffusivity.

Nakamura’s effective diffusivity is often written in terms of a ratio of squared length scales:

$$K_e \geq K_{el} \equiv k \frac{L^2}{L_0^2}$$

(5)

and we introduced the lower bound of the effective diffusivity $K_{el}$. $L_{eq}$ is an equivalent length greater than or equal to $L$, the length of the tracer contour (Shuckburgh and Haynes 2003); $L_0$ is the initial length of the contour; and $K_e = K_{nak}/L_0^2$. This form shows that the effective diffusivity exceeds the small-scale value if the tracer contour is elongated by the advecting flow:

$$K_e \geq= \kappa \frac{L^2}{L_0^2}$$

(6)

During the initial straining, before small-scale mixing sets in, the area between tracer contours is approximately conserved (as the flow is non-divergent), and one can estimate $L$ equivalently from tracers and particles (which do not experience mixing).

We can use the relationship in (6) to make the connection with the Lagrangian diffusivities. We think of the tracer contour as being made up of $N$ discrete particles. Then the squared length of the contour is given by

$$L^2 = \sum_{n=1}^{N-1} (r_{n+1} - r_n)^2 = \sum_{n=1}^{N-1} (x_{n+1} - x_n)^2 + (y_{n+1} - y_n)^2,$$

(7)

where $r_n = (x_n, y_n)$ is the position of the n-th particle. Clearly:

$$L^2 = N \langle \Delta r^2 \rangle,$$

(8)

where $\langle \Delta r^2 \rangle$ is the mean square spacing between the particles. This is the relative dispersion of particle pairs (e.g., Bennett, 2006). Thus if the area between tracer isolines is conserved, we have

$$K_{el} = \kappa \frac{\langle \Delta r^2 \rangle}{\langle \Delta r_0^2 \rangle}.$$  

(9)

So the lower bound effective diffusivity is proportional to the relative dispersion.
But how is the effective diffusivity related to the particle diffusivity? Following Taylor (1921), the Lagrangian diffusivity is given by:

$$K_1 = \frac{1}{2} \frac{d}{dt} <(r - r_0)^2 >,$$

(10)

where $r$ is the position of a particle, $r_0$ is its initial position and the brackets indicate an average over all particles. This applies to single particles, and accordingly we refer to (10) as the single-particle diffusivity. However, one can also define a relative diffusivity (or two-particle diffusivity):

$$K_2 = \frac{1}{4} \frac{d}{dt} < \Delta r^2 >,$$

(11)

(e.g., Batchelor and Townsend, 1956; Davis, 1985; Babiano et al., 1990). The factor of $1/4$ is arbitrary but useful, as described below. An important point is that the relative diffusivity, unlike the single-particle diffusivity, is Galilean invariant.

Now if the stirring is nonlocal (dominated by larger-scale eddies), the relative dispersion increases exponentially with time (Lin, 1972; Bennett, 1984; Babiano et al., 1990; LaCasce, 2008):

$$< \Delta r^2 >= < \Delta r_0^2 > e^{t/\tau},$$

(12)

where $\tau$ is a time scale, usually determined by the root mean squared shear. From (9), the effective diffusivity will also grow exponentially with time, with the same e-folding time scale, $\tau$. With exponential growth, the relative diffusivity is proportional to the relative dispersion (11). So the lower bound of the effective and relative diffusivities are proportional to one another

$$K_{el} = \kappa \frac{4\tau K_2}{\langle \Delta r_0^2 \rangle}.$$

(13)

But this equivalence follows from two assumptions: first, that the area is conserved between tracer contours and second, that the stirring is nonlocal. The relation will presumably break down if either assumption is violated. So, for example, the diffusivities should differ under local stirring, as occurs in a two-dimensional inverse-energy cascade or three-dimensional forward-energy cascade (e.g., LaCasce, 2008).

In numerical studies, the effective diffusivity asymptotes to a constant value when the small-scale diffusion is actively mixing away the tracer gradients (Nakamura, 2008). Area is no longer conserved between isolines, implying the lower bound in (6) is no longer useful. The relative dispersion, on the other hand, continues to grow. When particle separations are large enough, the pair velocities are uncorrelated and the relative diffusivity, defined with the prefactor of one-fourth, asymptotes to the single-particle diffusivity, $K_2 \rightarrow K_1$ (e.g., Babiano et al., 1990; LaCasce, 2008). At this point, relative dispersion grows linearly in time, as for a diffusive process. But as the effective diffusivity is constant, the two cannot be the same at later times (see (9) for the relation between the effective diffusivity and relative dispersion).

The Lagrangian diffusivities (the time derivative of dispersion) should also asymptote to constant values at later times, provided there are no long-term correlations in the velocities.
(Taylor, 1921). Yet there is no guarantee that the particle diffusivities will agree with the tracer-derived estimate. Indeed, the former derive purely from advective considerations while the latter are based on an areal integration, which effectively removes the advective term from the tracer equation. While the effective diffusivity is proportional to the small-scale diffusivity, the relative diffusivity is determined essentially by the scale and kinetic energy of the energy-containing eddies. The two diffusivities are expected to converge, if the rate at which tracers are homogenized is set by the large-scale eddies and not by small-scale diffusion. This probably happens in strongly turbulent fields where the large-scale eddies set the rate at which tracer filaments are generated. Once generated, the filaments are stretched and folded until they are homogenized by small-scale diffusion. A reduction of small-scale diffusion does not alter the rate of tracer homogenization, rather it results in thinner filaments that can be irreversibly mixed faster to keep up with the rate of filament generation.

Previous results suggest that the two diffusivities are the same, at least for some idealized flows. A collection of particles constitutes a tracer, and thus an initial distribution should evolve according to the same diffusion equation (3). Shuckburgh and Haynes (2003) examined this, computing numerical solutions to this equation, using the effective diffusivity diagnosed from a simple analytical flow field, and comparing the solutions to time-evolving distributions of particles advected by the same flow. The close agreement suggests that particles effectively obey the same diffusion equation. So the diffusivity measured by the particles and the tracer ought to agree.

We test this hereafter using numerical calculations of evolving tracer fields and particle distributions using a velocity field representative of the Southern Ocean.

3. The velocity field

The velocity at the surface is estimated from the sea-surface height slope measured by altimeters from space. We use sea-level anomaly maps from the combined processing of Ocean Topography Experiment (TOPEX) and European Remote Sensing Satellite-1 and 2 (ERS-1 and ERS-2) altimetry data with a temporal resolution of 10 days and a spatial resolution of 1/4° longitude × 1/4° latitude. We focus on the region upstream of Drake Passage between 103°–78°W and 30°–66°S, broadly the same area chosen for the DIMES campaign; a snapshot of sea-surface height from this region is shown in Figure 1. Conveniently, the ACC is nearly zonal in this region, so the cross-stream direction is simply north–south.

The sea-level anomalies are computed with respect to a three-year mean (from January 1993 to January 1996). The mean streamlines are computed from the sum of the mean geoid and the three-year time-mean sea-surface height from altimetry. The geoid model is described in Lemoine et al. (1998) and the altimetric data are described in Marshall et al. (2006) and Ferrari and Nikurashin (2010). The geostrophic relation is used to derive zonal and meridional geostrophic velocities from sea-surface height slopes,
Figure 1. Snapshot of sea-surface height (m) as estimated from the combined processing of the TOPEX, ERS-1 and ERS-2 altimetry for an ACC sector upstream of Drake Passage between 103°–78°W and 30°–66°S.

\[(u_g, v_g) = f^{-1}g(-\partial_y h, \partial_x h)\] where \(f\) is the Coriolis parameter and \(g\) the acceleration of gravity. The velocities are then interpolated onto a 1/10° resolution grid. We constructed two different velocity fields; an “eddy” velocity field, in which we calculate the geostrophic velocities using only the sea-surface height anomalies and a “full” velocity field, in which we add the zonal mean flow shown in Figure 2 (ignoring the very weak meridional mean flow) to the eddy velocity. The results described below do not change if we retain the spatial dependence of the mean flow.
The altimeter provides an estimate for the surface horizontal velocity, but one needs horizontal velocities at all vertical levels to estimate both the horizontal and vertical variations in the lateral diffusivity. Killworth and Hughes (2002) argue that the mean and eddy flows in the ACC have an equivalent-barotropic structure, i.e., the horizontal velocities at all levels can be reconstructed by multiplying the surface values by a structure function that depends only on depth, $\mu(z)$, defined as

$$\mu(z) = \frac{|u(x, y, z)|}{|u(x, y, 300)|}. \quad (14)$$

The equivalent-barotropic structure applies only to the geostrophic velocity, hence the velocity field is scaled to its value at $z = 300$ m below any Ekman flow. The structure function is computed from the output of the Southern Ocean State Estimate (SOSE; Mazloff et al., 2010), an eddy-permitting general circulation model of the Southern Ocean constrained to observations in a least-squares sense. The structure function $\mu(z)$ is calculated at each vertical level as a two-year average and a spatial average restricted to the area spun by the ACC in the region under study; the equivalent-barotropic model is meant to apply only in the ACC and not north of it (Killworth and Hughes, 2002). The structure function $\mu(z)$, shown in Figure 3, is then used to scale the surface geostrophic velocity in the whole domain (not just in the ACC latitude band) and produce a three-dimensional map of geostrophic velocity. We tested the skill of the equivalent-barotropic model in reproducing the horizontal velocity field in SOSE: the difference between the model horizontal velocity and the equivalent-barotropic model horizontal velocity is typically less than 20% in the ACC latitude band. The approach is less successful north and south of the ACC, where the error can be as large as 100%. The focus of this paper is mainly on dispersion in the ACC latitude
The equivalent-barotopic structure function $\mu(z) = \langle |u(x, y, z)|/|u(x, y, 300)| \rangle$ as a function of depth calculated from SOSE and averaged over the ACC latitude band. Note that the velocities are scaled relative to 300 m to avoid Ekman fluxes in the mixed layer.

Figure 3. The equivalent-barotopic structure function $\mu(z) = \langle |u(x, y, z)|/|u(x, y, 300)| \rangle$ as a function of depth calculated from SOSE and averaged over the ACC latitude band. Note that the velocities are scaled relative to 300 m to avoid Ekman fluxes in the mixed layer.

band, so the lack of skill in reconstructing the velocity in other regions is less important. Moreover, our goal is to compare different diffusivity estimates using the same velocity field, and it is not too important if some aspects of the field are not realistic.

This equivalent-barotropic map of geostrophic velocities has advantages over using the full three-dimensional velocity field from numerical models such as SOSE: first, it provides a simple kinematic framework to test our theory—for example, we can easily modify the mean flow without affecting the phase speed of the eddies; and second, we can easily increase the resolution of the numerical code used to advect floats and tracers, so as to minimize spurious numerical diffusion. Even though this velocity field is highly idealized, it captures the key kinematic properties of the full velocity field and generates diffusivities very similar to those estimated by Abernathey et al. (2010), who computed diffusivities advecting tracers with the SOSE three-dimensional velocity field.

All diffusivity estimates converge in less than a year, as shown below. We focus on dispersion in the meridional direction, as noted; fluid parcels experience meridional displacements of 100–200 km during the first year.

The advection of tracers and floats is purely horizontal, i.e., vertical velocities are ignored. The vertical displacements experienced in a year are less than 10–100 m. Thus the lateral dispersion is hardly affected by the additional vertical displacement. The
vertical velocities are nevertheless important because they permit horizontal divergence \((\partial_x u + \partial_y v = -\partial_z w \neq 0\) because of the latitudinal variation of the Coriolis parameter, the presence of boundaries, and so on). Over long times, fluid particles would artificially cluster in regions of convergence and drift away from regions of divergence. We therefore make the velocity field nondivergent by adding a divergent correction, \(\Delta \chi\), to the altimetric velocity; i.e., we create a velocity field \(u = u_g + \Delta \chi\), where \(u_g\) is the geostrophic velocity. The divergent correction further imposes no-normal flow conditions at the continental and north-south boundaries of the computational domain. Periodic conditions are instead enforced at the east-west boundaries. The implementation of the nondivergent correction is described in detail in Marshall et al. (2006). In practice the adjustment leads to very small changes in the geostrophic velocity field primarily at the boundaries. The estimates of dispersion are hardly sensitive to these corrections, except close to the meridional boundaries.

4. Methods

We now compare the effective diffusivity of Nakamura (1996) with the single-particle and two-particle diffusivities. We also estimate the diffusivity from the dispersion of tracer patches. As the effective diffusivity measures mixing across the mean flow, which is primarily zonal in the region considered here, we focus solely on the meridional components of the diffusivities.

We compute the effective diffusivity \(K_e\) by advecting a tracer with the equivalent-barotropic velocity field shown in Figure 1 and using a constant numerical diffusivity \(\kappa\). The approach is identical to that described in Marshall et al. (2006) and Ferrari and Nikurashin (2010) and the reader is referred to those papers for technical details. This requires careful consideration of the implicit mixing due to the numerical scheme that increases the value of \(\kappa\) to be used in (4)—we show in the Appendix that the implicit mixing changes with depth and these variations must be taken into account.

The meridional component of the single-particle diffusivity is defined as

\[
K_{1y}(y_0, t) = \frac{1}{2} \frac{d}{dt} \langle (y(t) - y_0)^2 \rangle, \tag{15}
\]

where \(y(t)\) is the meridional position of a particle released at \(y_0\) at \(t = 0\) and \(\langle \cdot \rangle\) is the average over all particles. We anticipate that the diffusivity will vary with latitude, so we express it as a function of the initial position, \(y_0\).

The eddy diffusivity is equal to the integral of the Lagrangian autocorrelation function:

\[
K_{1y}(y_0, t) = \int_0^t R_{vv}(y_0, \tau) \, d\tau \quad \text{where} \quad R_{vv}(y_0, \tau) = \langle v_L(y_0, \tau)v_L(y_0, 0) \rangle, \tag{16}
\]

and \(v_L(y_0, t)\) is the Lagrangian velocity of a particle. Assuming that the correlation goes to zero after a given period of time and that its integral is finite, the diffusivity \(K_{1y}(y_0, t)\) will asymptote to a constant value (Taylor, 1921).
The relative (two-particle) diffusivity is defined analogously:

\[ K_{2y}(y_0, \Delta r_0, t) = \frac{1}{4} \frac{d}{dt} \langle (y_i(t) - y_j(t))^2 \rangle, \quad (17) \]

where \( y_i(t) \) and \( y_j(t) \) are the meridional positions of particles \( i \) and \( j \) released within a distance \( \Delta r_0 \) of each other (\( y_0 \) is the initial condition of either the \( i \) or \( j \) particle); the ensemble average is taken over many such pairs. As noted, we use the pre-factor of one-fourth to ensure that the two-particle diffusivity asymptotes to the single-particle value at long times (e.g., Davis, 1985).

Trajectories are generated by advecting numerical particles with the velocity field described above. The floats are initialized on a regular grid with an initial spacing of 0.2° and advected for one year using a fourth-order Runge-Kutta scheme. Float positions are saved every 0.6 days. We impose a periodic boundary condition in the zonal direction, so that floats leaving the eastern or western boundary reenter from the opposite side. This ensures that floats do not leave the computational domain, increasing the length of the particle time series. A no-normal flow condition is imposed at the northern and southern boundaries (Section 3), so the floats are unable to leave there.

A few sample trajectories illustrate the different kinematic regimes in the subtropical gyre and in the ACC (Fig. 4). In the subtropical gyre, the floats have a random motion. In the ACC, on the other hand, the particles exhibit coherent, meandering motion. This meandering plays an important role in the subsequent particle statistics. Note that after 150 days many floats in the ACC would have left the domain from the east, were they not reintroduced from the west (reentering floats are not shown in the figure).

Lastly, there is the diffusivity derived from the dispersion of a cloud of tracer. The centered second moment of the cloud is equivalent to the relative dispersion of all pairs of particles in the cloud. When the pair motions become uncorrelated, the centered second moment of the cloud increases linearly in time, as for a diffusive process; at this point the diffusivity can be obtained from the time derivative of the centered second moment (Garrett, 1983). The meridional component is defined

\[ K_{ty} = \frac{1}{2} \frac{\partial \sigma_y^2}{\partial t} = \frac{1}{2} \frac{\partial}{\partial t} \frac{\iint (y - y_c)^2 C(x, y) dx dy}{\iint C(x, y) dx dy}, \quad (18) \]

where \( \sigma_y^2 \) is the second moment of the tracer concentration in latitude and \( y_c \) is the meridional position of the baricenter of the tracer patch,

\[ y_c = \frac{\iint y C(x, y) dx dy}{\iint C(x, y) dx dy}. \quad (19) \]

We advected tracer patches with the same velocity field and numerical scheme described before. We used two different initial conditions: zonally uniform stripes with a meridional
Figure 4. Numerical trajectories for two clusters of approximately 100 particles released between 103°–103.5°W and 40°–46°S (upper cluster), and 103°–103.5°W and 56°–62°S (lower cluster). Particle trajectories are shown for the first 150 days. When particles leave at the eastern or western boundary, they are reintroduced from the opposite side for the diffusivity calculations. Particles reentering the domain from the west are not shown here to avoid cluttering the figure.

Gaussian profile and a standard deviation of 0.5° latitude, and isotropic Gaussian blobs with a 0.5° standard deviation in longitude and latitude. The zonal stripes are most appropriate for estimating meridional diffusivities for the whole Pacific sector, while the blobs are an attempt to reproduce an anthropogenic tracer release in the real ocean.

5. Results

a. Initial behavior

We consider first the initial behavior of the effective diffusivity, and test the relation to the relative dispersion given in (9). To do this, we calculate the relative dispersion of a set
Figure 5. Effective diffusivity $K_e$ defined in (5) at early times (dotted-dashed lines) as compared with relative diffusivity of pairs of particles released along the same latitude line for two different sets of particles, one set released 0.02° apart (dashed lines) and the other set released 0.1° apart (solid lines). The upper panel is for 45°S and the lower for 59°S, where the latitude is defined as the equivalent latitude for $K_e$ (see Appendix) and as the latitude at which particles are released for the relative diffusivity.

Examples at two latitudes are shown in Figure 5. The particle diffusivity, defined as $\kappa \langle \Delta r^2 \rangle / \langle \Delta r_0^2 \rangle$, is shown by the solid and dashed curves and the effective diffusivity by the dash-dot curve. The solid curve is for pairs with an initial separation of 0.1° and the dashed curve for an initial separation of 0.02°.

The upper panel shows the results from 45°S, north of the ACC. The three curves track one another closely for the first 10 days, and growth is nearly exponential. Exponential growth is to be expected (e.g., Bennett, 1984), as the initial particle spacing is below the resolution of the velocity field, implying that the velocity spectrum is very steep at these scales (see also Poje et al., 2010). After the initial period, the effective diffusivity grows slower (and saturates, soon after); the relative dispersion, on the other hand, continues to increase. Of these two, the dispersion with the smaller initial separation (the dashed curve) increases fastest.
The latter effect can be understood as follows. All the curves have the same initial value, equal to \( \kappa \). Imagine that the exponential growth proceeds to a scale, \( L \); this could be the deformation radius, for example. At that scale, the particle estimate of the dispersion from (6) is \( \kappa L^2 / \Delta r_0^2 \). So the smaller the initial spacing, the larger the diffusivity at scale \( L \). In addition, the exponential growth is clearest with the \( \Delta r_0 = 0.02^\circ \) spacing, as the pairs experience the interpolated velocity differences for a longer period.

The comparison at 59\(^\circ\)S, in the ACC latitude band, is not as good. The particle dispersion increases exponentially and the two curves with different initial separations agree with one another at early times, as before. But both grow more rapidly than the effective diffusivity. The latter asymptotes to a value near 500 m\(^2\)s\(^{-1}\) by day 25, while the particle-based estimates are much larger.

This suggests that the mean flow causes the effective diffusivity to diverge faster from the area-conserving estimate given in (6). This is due in part to the zonal dispersion of the particles by the mean flow. Rhines and Young (1983) show that tracers are rapidly homogenized along mean streamlines, so after a very short transient the tracer contours reflect only the cross-flow diffusivity. But the two-particle dispersion used to evaluate \( L^2 \) also includes the zonal dispersion, and this is increasing faster due to the mean shear.

In summary, the effective diffusivity behaves like the relative dispersion of particle pairs initially. But at later times, when the effective diffusivity asymptotes, the similarity no longer holds. This is due in part to the nonconservation of area between tracer contours and because the effective diffusivity measures only the cross-flow diffusivity. Thus having a mean zonal flow worsens the agreement and it is more sensible to focus on the cross-stream particle diffusivity at later times.

b. Asymptotic behavior; effective diffusivity

Now we turn to the diffusivities at later times. Shown in Figure 6 is the asymptotic value of averaging the effective diffusivity, \( K_e \), as a function of latitude at the surface and at 1,500 m. The asymptotic value is obtained by averaging the diffusivity over the period from 150 to 365 days, after the measure has leveled off. At the surface the effective diffusivity is close to 1,000 m\(^2\)s\(^{-1}\) north of the ACC, while it drops to 500 m\(^2\)s\(^{-1}\) in the core of the current. In contrast, the effective diffusivity at depth is largest in the core of the ACC where it reaches 1,000 m\(^2\)s\(^{-1}\) and is smaller to the north. These patterns are consistent with those found by Marshall et al. (2006) and Abernathey et al. (2010).

The observed latitudinal and vertical variations in the effective diffusivity support the notion that the mean flow suppresses mixing (Ferrari and Nikurashin, 2010). To test this, we advected the particles with a velocity field with the zonal mean flow (Fig. 3) removed: the “eddy” velocity field introduced in Section 3. The resulting estimates of \( K_e \) are shown in Figure 6. Without a mean flow, \( K_e \) peaks in the core of the ACC, where the eddy kinetic energy (EKE) is largest, both at the surface and at depth. Such behavior is consistent with mixing length arguments in which the diffusivity is proportional to the eddy length scale times the square root of the kinetic energy (Holloway, 1986; Keffer and Holloway, 1988).
Figure 6. Effective diffusivity $K_e$ (solid blue lines), defined in (5), and tracer-based diffusivity $K_{ty}$, defined in (18), from the spreading of tracer stripes (solid black lines) and tracer patches (solid red lines). Also shown is the effective diffusivity for a tracer advected with the eddy velocity only (dashed blue lines). (a) Diffusivities computed with the surface geostrophic velocity field. (b) Diffusivities calculated with the equivalent-barotropic velocity field rescaled for $\sim 1,500$ m.

The eddy length scale varies little with depth and latitude, so that $K_e \propto \sqrt{EKE}$. However, the addition of a mean flow breaks the scaling at the surface (at depth the mean flow is very weak). The suppression is more pronounced in the ACC where the mean flow is largest. The suppression of mixing by the mean flow is the focus of a companion paper (Klocker et al., 2012).
Figure 7a shows the full latitude-depth map of $K_e$ for the Pacific sector under study. In the ACC latitude band, between 55° and 65°S, the effective diffusivity is suppressed by the mean flow at the surface and has a subsurface maximum around 1,500 m where the mean flow becomes weak. To the north, where the mean flows are weaker, the effective diffusivity is largest at the surface where the EKE is largest.

c. Moment method: dispersion of a tracer stripes and patches

Next we consider the diffusivities as estimated from the growth of a patch of tracer. Figure 6 shows the diffusivity for a series of zonal “stripes” of tracer, released at different
latitudes at the surface and at 1,500 m. The growth rate of $\sigma_y^2$ becomes linear in time after 150 days. We estimate the diffusivity $K_{ty}$ as a least square fit of the change in $\sigma_y^2$ versus time between 150 and 365 days. The $K_{ty}$ values estimated from (18) agree well with the effective diffusivities $K_e$ at all latitudes, despite some discrepancies at the northern and southern boundaries, where edge effects suppress the dispersion.

Results from the Gaussian patch releases are also shown in Figure 6. Tracer patches were released at 100°W at a set of different latitudes spaced by one degree, at the surface and at 1,500 m. The initial transient is much more variable in these simulations, but after 150 days the dispersion is increasing linearly and diffusivities are computed in the same way as done for the tracer stripes. Agreement with the previous estimates is very good. Again discrepancies are visible at the north and south edges of the domain, and also between 53° and 54°S. The latter is the result of the rapid zonal variations in eddy diffusivity at the northern edge of the ACC.

Note that while the effective diffusivity and the zonal stripes yield a zonal average of the diffusivity, the Gaussian patches at early times can be used to detect longitudinal variations. Averaging the results from patches released across the domain in the zonal direction yields the same diffusivity as with the stripe (not shown here). Note that agreement between different methods is achieved because we can sample all of the tracer (periodic boundary conditions ensure that the tracer never leaves the domain). Such sampling cannot be done in field experiments.

d. Particle dispersion

Lastly, we consider diffusivities derived from particle trajectories. We begin with single-particle diffusivity, as this is the measure used most frequently in observational studies. We calculated $K_{1y}(y_0, t)$ using (15)—estimating the diffusivity by integrating the velocity autocorrelation yielded identical results. We averaged the diffusivities for all particles deployed in regions 25° in longitude (the width of the domain) by 2° in latitude. This averaging stripe is substantially larger than the typical eddy scale in the Southern Ocean of $O(100)$ km. As the mean velocity is purely zonal, we do not need to separate mean and eddy velocities in the meridional direction.

Following Davis (1991), we treat every point at which a float position is saved as a starting position for a new trajectory, substantially increasing the number of pseudotrajectories. The method is illustrated graphically in Figure 8: every orange dot shows a point at which a float position is saved, and it is treated as the starting position for a new trajectory. The technique is described by Griesel et al. (2010) and represents a slight modification of the technique used in Colin de Verdiere (1983), Poulain and Niiler (1989) and Zhurbas and Oh (2003), among others. The single-particle diffusivities converge to a constant within half a year in the subtropical gyres and sooner elsewhere. Hence we consider all trajectories with a minimum length of 160 days and estimate the diffusivity as an average over the last 20 days of all available pseudotrajectories. The averaging window is different from tracer-based
estimates because particles drift too far from their release latitude after 160 days to allow local estimates of diffusivities.

Examples of single-particle diffusivities are shown in Figure 9 for (a) particles released in a 2° stripe in the subtropical gyre (45°S±1°) and (b) particles released in a 2° stripe in the ACC (59°S±1°). In line with the previous calculations of effective diffusivity, we use both the full velocity field (solid lines) and the eddy velocity field (dashed lines). These stripes were chosen because they are representative of regions with (a) weak mean flow and (b) strong mean flow (see Fig. 4 for the different behavior of trajectories in these regions). The shaded areas around the single-particle diffusivities show the 2σ errors estimated using a bootstrapping technique. For comparison, the corresponding Lagrangian autocorrelation functions, $R_{vv}$, are shown in Figure 10.

In the subtropical gyre domain, the diffusivities based on particles advected by the eddy velocity field asymptote to a constant value of $\approx 2,000$ m²s⁻¹ after 20 days (Fig. 9a). The diffusivity for the particles advected with the full velocity behaves similarly initially, but only reaches a value of $\approx 1,700$ m²s⁻¹; thereafter it decreases slowly. This decrease is related to a negative lobe in the velocity autocorrelation, $R_{vv}$ (Fig. 10a).

The difference between the diffusivities based on the eddy and mean velocity fields is more evident in the ACC (Fig. 9b). The velocity autocorrelations for the experiments with and without a mean flow have negative lobes, but the addition of a mean flow results in a much more pronounced lobe. As a result, both diffusivities decrease after first reaching a maximum, at roughly $4,000$ m²s⁻¹. But the diffusivity for the mean velocity falls much more, eventually asymptoting to a value between 500 and 1,000 m²s⁻¹. The diffusivity for

5. Bootstrapping consists of first subsampling the approximately 1,000 floats deployed in every stripe 100 times, allowing for duplicates, and then using each of these subsets of floats to calculate a diffusivity. The 2σ errors are the standard deviations of the $K_s$ estimated from the 100 realizations (see Griesel et al., 2010).
Figure 9. Single-particle diffusivity, $K_{1y}$ (15) for particles released in 2° stripes in (a) the subtropical gyre ($45° S \pm 1°$) and (b) in the ACC ($59° S \pm 1°$), both for the full velocity field (solid lines) and for the eddy velocity field (dashed lines). The shaded error bars show 2σ errors estimated with a bootstrapping technique.

The eddy velocity is two-to-three times larger. The difference is again linked to a negative lobe in the autocorrelation, which is most pronounced with the mean flow.

The link between mean flows and negative lobes is explained in the companion paper (Klocker et al., 2012), but it is easily understood. The mean flow in the ACC is directed eastward flowing at 10 cm s$^{-1}$, while the eddies drift much slower at 1–2 cm s$^{-1}$. Hence the mean flow advects particles around nearly stationary eddies, resulting in back and forth meandering motions. The negative lobe in the velocity autocorrelation is the signature of trajectories that meander back and forth from their release latitude. These meanders do
not contribute any irreversible mixing and must not be included in the calculation of the diffusivity. This is achieved by integrating the velocity autocorrelation past the negative lobe.

Now we use (15) to compute meridional profiles of diffusivities for velocities at the surface and at 1,500 m depth. We employ the 25° longitude × 2° latitude stripes described above, but with one stripe every 1° of latitude (i.e., the stripes overlap). Again, the deep velocity field is obtained by multiplying the surface velocity by the equivalent-barotropic structure function $\mu(1,500 \text{ m})$ (see Fig. 2).
Figure 11. Effective diffusivity $K_e$ (blue lines), as defined in (5), single-particle diffusivity $K_{1y}$ (solid black line), as defined in (15), and two-particle diffusivity $K_{2y}$, as defined in (17), for tracers and particles advected with (a) the surface geostrophic velocity and (b) the velocity at $\sim 1,500$ m, i.e., the surface geostrophic velocity multiplied by 0.4 according to the equivalent-barotropic model for that depth (see Fig. 2). Dashed blue lines are effective diffusivity $K_e$ for a tracer advected with the eddy velocity only.

The results are plotted in Figure 11, along with the effective diffusivities found previously. The estimates agree within the errors at all latitudes, at both depths. Both estimates capture the suppression by the strong ACC flow at the surface. We therefore can answer positively the question we posed in the introduction: for the flow regimes observed in the Southern Ocean, estimates of diffusivity based on tracers and particles are equivalent. This is encouraging,
because numerical models need the diffusivity that describes the rate at which tracers are homogenized, while direct estimates of diffusivity in the ocean rely on float dispersion (especially below the surface). Agreement between the two estimates means that we can compare models and observations.

In a number of previous studies, the single-particle diffusivity was estimated either from the maximum value achieved by $K_{1y}$ at short times (e.g., Zhurbas and Oh, 2003) or, equivalently, by integrating to the first zero crossing of the velocity autocorrelation (e.g., Freeland \textit{et al}., 1975; Poulain and Niiler, 1989). The reasoning is that the error in the diffusivity grows in time, so that the estimates at longer lags are less certain. However, ignoring the contribution of the negative lobe results in a substantial overestimate of $K_{1y}$. An option is rather to fit the autocorrelation to the product of an exponential and a cosine (Garraffo \textit{et al}., 2001; Sallée \textit{et al}., 2008). This is in line with the present findings.

Integrating our velocity autocorrelations to the first zero crossing or equivalently using the maximum yields much larger diffusivities (not shown). Moreover, there was little difference between the diffusivities found using the full velocity and the eddy velocity. Thus using the first zero crossing method effectively misses the suppression of eddy diffusivity by the mean flow.

How many particles are required to obtain convergent estimates, i.e., to fully resolve the negative lobes? In the calculations above, we used approximately 1,000 floats per stripe, a quantity that is unrealistic by observational standards. From theory (e.g., Davis, 1991), the error in the diffusivity is expected to decrease as $n^{-1/2}$. We checked this by recalculating the diffusivities using smaller numbers of particles both for particles released in $2^\circ$ stripes in the subtropical gyre ($45^\circ S \pm 1^\circ$) and for particles released in $2^\circ$ stripes in the ACC ($45^\circ S \pm 1^\circ$). Errors were calculated by the same bootstrapping technique used for Figure 9. The relative errors defined as $2\sigma/K_{1y}$ are shown in Figure 12, where $\sigma$ is the standard deviation calculated from bootstrapping, plotted against the number of particles used. The results are consistent with a decrease proportional to $n^{-1/2}$ (although the decrease is somewhat faster with large numbers of particles).

Lastly, we consider the diffusivities derived from pairs of particles. These are calculated as with the single-particle diffusivities, but now at every point at which a float trajectory is saved we find all other trajectories that are within a specified radius. We then calculate two-particle diffusivities using the meridional distance between those floats according to Eq. (17). This method thus involves using “chance pairs,” or pairs of particles not deployed together (Morel and Larcheveque, 1974; LaCasce, 2008). We use particle trajectories with a minimum length of 60 days and average over the last 20 days. The resulting two-particle diffusivities, together with the single-particle diffusivities from the same stripe, are shown in Figure 13.

As noted previously, the two-particle diffusivity (defined with a pre-factor of one-fourth) should asymptote to the single-particle diffusivity after the pair velocities become decorrelated. This is the case (Fig. 13). However, the two-particle diffusivity differs at early times. This can be seen in Figure 14, in which we changed the initial spacing of the particle pairs.
Figure 12. Relative error $2\sigma/K_{1y}$ of the single-particle diffusivity $K_{1y}$ (15), where $\sigma$ is the standard deviation calculated from bootstrapping with 100 subsamples of $n$ particles. The errors are shown for particles released in a $2^\circ$ stripe in the subtropical gyre ($45^\circ$ S $\pm 1^\circ$) (blue) and particles released in a $2^\circ$ stripe in the ACC ($59^\circ$ S $\pm 1^\circ$) (red) for the surface (solid lines) and 1,500 m (dashed lines). The solid black line shows a line with slope of $n^{-1/2}$.

between $0.2^\circ$ and $0.8^\circ$. At $45^\circ$S (Fig. 14a), the closer the initial pairs, the more slowly the diffusivity asymptotes to the final value. This is because it takes longer for pairs to separate to a distance at which their motion is no longer correlated. The effect is more dramatic at $59^\circ$S, where there is a strong mean flow (Fig. 14b); we see that the overshoot is greatly diminished for closer pairs. For the smallest initial separation of $0.2^\circ$, there is barely any overshoot at all.

The reason for the lack of overshoot in $K_{2y}$ is that relative dispersion, unlike single-particle dispersion, is Gallilean invariant. Thus a pair of particles moves with the meandering flow (Fig. 7), and the diffusivity measures only their separation. The closer the particles are initially, the more faithfully they track one another through the meanders.

The pair diffusivities as a function of latitude are shown in red in Figure 11. We see that the estimates are consistent with both those from single particles and with the effective diffusivities. Thus all three methods yield consistent values.

6. Implications for observational estimates of eddy diffusivities

A motivation for the present work was to see how many floats are required to distinguish lateral and vertical variations in eddy diffusivities in the real ocean. In DIMES, both floats and an anthropogenic tracer have been released to infer eddy diffusivities. The tracer was released at $58^\circ$S, $107^\circ$W, between the Polar Front and the Subantarctic Front on the 27.9 kg m$^{-3}$ neutral density surface, which is at a depth of approximately 1,500 m (see (Ledwell et al., 2011) for details on the tracer release). Due to the filamentation and the
Figure 13. Time evolution of single-particle diffusivities $K_{1y}$ (15), solid line) and relative diffusivities $K_{2y}$ (17), dashed line) for (a) particles released in a 2° stripe in the subtropical gyre (45°S ±1°) and (b) particles released in a 2° stripe in the ACC (59°S ±1°). Shading shows uncertainties estimated by a bootstrapping technique.

Sparse sampling of the tracer in time (i.e., every 6–12 months) and in space (i.e., only part of the tracer is found using shipboard CTDs along the ship tracks), it is challenging to calculate diffusivities from the tracer using the methods described above. In addition to the tracer, 150 isopycnal RAFOS floats have been released between 54°–60°S, 105°W, on two isopycnal surfaces: 100 on the same neutral density surface as the tracer and 50 on the 27.2 kg m$^{-3}$ neutral density surface (at a depth of approximately 500 m). These two density surfaces were chosen to see if eddy mixing is indeed suppressed in the shallow ACC relative to eddy diffusivities at mid-depth, as found in our study (e.g., Fig. 7).
Figure 14. Time evolution of two-particle diffusivities $K_{2y}$ (17) for a set of different initial separations shown in the legends in units of latitude degrees for (a) particles released in a 2° stripe in the subtropical gyre (45°S ±1°) and (b) particles released in a 2° stripe in the ACC (59°S ±1°).

To estimate the number of floats necessary to assess this vertical variation in the real ocean, we advect synthetic floats using the same velocity field as above, with the only difference that floats exiting the domain are not allowed to reenter (in the case of DIMES, these floats are lost past Drake passage). The velocity field for both surfaces is derived by scaling the surface geostrophic velocity field according to the equivalent-barotropic scale factors shown in Figure 2 [i.e., $\mu (500 \text{ m}) \sim 0.9$ and $\mu (1,500 \text{ m}) \sim 0.4$]. The diffusivities are computed for a stripe in the ACC, which extends from 54°S to 62°S, and a stripe north of the ACC, which extends from 42°S to 50°S: both stripes span the whole domain in longitude.
These stripes are larger than the stripes used above to increase the Lagrangian statistics per stripe as needs to be done in real experiments. We also consider a stripe to the north of the ACC, even though no floats in DIMES were released in this region, to see if one can distinguish the eddy diffusivities in the ACC and to the north using float numbers like those in DIMES. On both surfaces floats are initialized every 0.2° as for previous calculations, giving approximately 5,000 floats per stripe. The error bars are the 5th and 95th percentiles calculated using a bootstrapping technique with 100 subsamples. We use subsample sizes of (a) 50 floats, (b) 150 floats and (c) 1,000 floats. The reason for using percentiles here rather than 2σ errors as above, is that due to the small numbers of floats the distributions are not very Gaussian. The error estimates are shown as gray shaded areas in Figure 15.

The error bars in Figure 15 show that with 50 or 150 floats, it is not possible to detect differences in the eddy diffusivities between the two latitudes and two depth levels with any significance. With 1,000 floats however, one can resolve with statistical significance the latitudinal and vertical variations in the diffusivity. This suggests that the 150 floats deployed in DIMES are not sufficient to resolve the lateral and vertical variations, if they are present. In addition, note that the DIMES floats are not deployed homogeneously as in our calculations. Hence the errors shown here are a lower limit for the errors expected from float releases in DIMES.

7. Summary and discussion

We have calculated lateral diffusivities for synthetic particles advected with a proxy velocity field. The latter derives from sea-surface height measurements from the South Pacific, in a region west of Drake Passage. The geostrophic surface velocities were adjusted to yield a nondivergent field, and the velocities were projected downward in the water column, assuming an equivalent-barotropic structure.

We calculated the diffusivities in three ways: (1) by advecting a tracer with the altimetry-based velocity field to estimate the “effective diffusivity” (Nakamura, 1996), (2) from the second moment of the tracer cloud and (3) using single- and two-particle diffusivities. The effective diffusivity measures the cross-stream component, so we focused on the meridional diffusivities for the others, as the mean flow (the ACC) is zonally oriented in the region.

We show that the effective diffusivity at early times is proportional to the relative dispersion (between pairs of particles). At later times, the relation breaks down as small-scale mixing violates area conservation between tracer isolines. However, at the later times the effective diffusivity agrees well with the meridional diffusivity estimated both from the tracer cloud and from the particles. While our analysis focussed on the Southern Ocean, the agreement is expected to hold in other parts of the world’s oceans.

The effective diffusivity is most useful for satellite-derived velocity fields, such as this, or for model fields; it is probably not practical with in situ tracer deployments. The moment method has been used previously with a deployed tracer (e.g., Sundermeyer and Price, 1998), but obtaining sufficient sampling is also an issue. Thus float-or drifter-based studies
Figure 15. Single-particle diffusivity $K_{1y}$ (15) for particles released in a stripe north of the ACC (a) at 500 m and (b) at 1500 m (the stripe extends from 44° to 48°S), and for particles released in a stripe in the ACC (c) at 500 m and (d) at 1500 m (the stripe extends from 56° to 60°S). Gray shading shows the 5th and 95th percentiles determined with a bootstrapping technique with 100 subsamples, using 50 floats (dark gray), 150 floats (medium gray) and 1,000 floats (light gray).
are still the most desirable. The present results demonstrate that the float-derived estimates are consistent with the others, as long as they are calculated correctly.

Abernathey (2012) further shows that the effective diffusivity is equivalent to the eddy diffusivity based on a flux-gradient relationship across the mean current as per (1). His results are also obtained by numerically advecting tracers with satellite-derived velocity fields in regions where the mean ocean flows are primarily zonal. This result nicely complements ours, and we can conclude that all estimates of diffusivities based on floats and tracers converge for the Southern Ocean flow regime considered in this paper.

A critical issue, seen clearly here, is that a mean flow suppresses the cross-stream diffusivities (e.g., Ferrari and Nikurashin, 2010; Naveira Garabato et al., 2011). One finds that the particle-based diffusivity reaches a maximum value before decreasing to a lower asymptotic limit. This reduction, often seen in observations, reflects a negative lobe in the velocity autocorrelation. Physically, this corresponds to “meandering” motion—particles being advected first across the mean flow and then returning some distance back toward their starting location. Thus the initial maximum is a transient advective feature and does not reflect the true mixing. Indeed, a similar overshoot is not seen with the effective diffusivity. Given this, using the maximum diffusivity, or equivalently integrating the autocorrelation to the first zero crossing, yields artificially large diffusivities.

There are two ways around this. One is to average the diffusivity after the initial transient phase, i.e., after it has reached the lower asymptotic limit. This means choosing an “intermediate” averaging period, after the initial transient but before the measurement errors have grown too large (e.g., Koszalka and LaCasce, 2010). The second is to use the two-particle diffusivity, which relates to the separation between pairs of particles. As both particles in the pair experience the initial meander, the relative diffusivity is devoid of the initial maximum provided the initial pair separation is small enough. However, this requires having a sufficient number of pairs to obtain reliable statistics.

Our results for the Pacific sector suggest that the number of particles or particle pairs necessary to resolve the vertical and horizontal variations in eddy diffusivities are in the hundreds. The CARTHE experiment (Consortium for Advanced Research on Transport and Hydrocarbon in the Environment), (www.carthe.org) underway in the Gulf of Mexico, uses hundreds of drifters, and the numbers are likely to increase as the cost of drifters decreases further. However, these numbers are prohibitively large for most field experiments that rely on subsurface floats like DIMES. Thus float-derived estimates should be used in conjunction with other information to quantify the absolute values and the vertical and lateral structure of eddy diffusivities. This could come from the release of a tracer patch, such as in DIMES; satellite-derived geostrophic velocity fields; and high-resolution numerical models. The challenge is to learn how to combine such diverse data sets to obtain statistically robust estimates of diffusivities.

Alternatively there are intriguing new ideas on how to use the geometrical shape of whole trajectories to infer mixing rates (e.g., Thiffeault, 2010). Noboru Nakamura (pers. comm.) has also suggested that one may be able to estimate the effective diffusivity using a
combination of floats and tracer measurements. Whether such approaches will alleviate the prohibitive demands on float numbers remains an open question and a worthwhile avenue for future studies.

We note too that the present study was greatly simplified by having a purely zonal mean flow in the region of interest. Thus we were able to focus on the meridional component of the diffusivity, and because values were averaged along the whole channel, we did not have to worry about skew fluxes/stokes drifts. Having a nonzonal mean flow further demands isolating the cross-flow component. This can be achieved, for example, via a principal axis decomposition on the symmetric portion of the diffusivity tensor, with the cross-flow diffusive component represented by the minor principal component (Zhurbas and Oh, 2003, 2004). But the present comments still apply in relation to that component—one must take account of the negative lobe.

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APPENDIX

To advect a numerical tracer, we use the offline capabilities of the Massachusetts Institute of Technology general circulation model (MITgcm; Marshall et al., 1997) with the nondivergent velocity field described above and solve the tracer advection-diffusion equation

$$\frac{\partial}{\partial t} C + u \cdot \nabla C = \kappa \nabla^2 C,$$

(20)

where $C$ is the tracer concentration and $\kappa$ is the explicit numerical diffusivity. For the tracer advection we use an Adams-Bashforth time-stepping scheme and a centered second-order advection scheme to advect the tracer for one year. The domain is zonally periodic with no-flux boundary conditions imposed at the northern and southern boundaries. The initial tracer concentration increases linearly with latitude, with values of zero at the southern boundary and values of one at the northern boundaries. As shown by Shuckburgh et al. (2009), the calculations of effective diffusivities are not very sensitive to the tracer initial condition.

The most problematic part in calculating effective diffusivities is the total numerical diffusivity. For an artificial tracer advected by a numerical model, this is the sum of the explicit and implicit numerical diffusivities. Without knowing the total numerical diffusivity but assuming that it is constant, one can determine the spatial structure of $K_e$, but to compute magnitudes of effective diffusivities one needs an estimate of the total numerical diffusivity (Shuckburgh et al., 2009). Marshall et al. (2006) show that the estimate of $K_e$ becomes independent of numerical diffusivity only for large Péclet number, with $Pe = U L_{eddy}/\kappa_{total}$,
where $U$ is the characteristic scale of the velocity, $L_{\text{eddy}}$ is an eddy length scale and $\kappa_{\text{total}}$ is the total numerical diffusivity. This would suggest the use of a small $\kappa$ for our calculations. On the other hand, using a $\kappa$ that is too small introduces implicit numerical diffusion generated by noise on the grid scale, which acts to increase $\kappa_{\text{total}}$. For every vertical level we choose an explicit numerical diffusivity small enough to ensure that the estimate of $K_e$ is independent of the numerical diffusivity, but large enough to keep the implicit numerical diffusivity small. To estimate the total numerical diffusivity inherent in the advection of the artificial tracer we use the tracer variance equation,

$$\frac{1}{2} \frac{\partial \langle C^2 \rangle}{\partial t} = -\kappa_{\text{total}} \langle |\nabla C|^2 \rangle, \quad (21)$$

where $\langle \cdot \rangle$ indicates the average over the domain. $\kappa_{\text{total}}$ is the total numerical diffusivity necessary to explain the decay of the observed tracer variance $\langle C^2 \rangle$.

$K_e$ is estimated by advecting the tracer with an explicit numerical diffusivity of $10 \text{ m}^2\text{s}^{-1}$. Using (21) gives us the numerical background diffusivity inherent in the numerical advection code, $\kappa_{\text{total}}$, which varies from $30 \text{ m}^2\text{s}^{-1}$ at the surface to $11 \text{ m}^2\text{s}^{-1}$ at depth. Note that this variation of $\kappa_{\text{total}}$ with depth can easily be accounted for in the two-dimensional calculations performed in this study, but might lead to serious issues in three-dimensional calculations in which one value for $\kappa_{\text{total}}$ is used at all depths.

We then use (5) to calculate $K_e$, where $L_0(y_{\text{eq}})$ is the width of the domain at the equivalent latitude $y_{\text{eq}}$, and $L_{\text{eq}}^2$ can be written as (see Shuckburgh and Haynes, 2003, for a derivation)

$$L_{\text{eq}}^2 = \left[ \frac{1}{\partial A} \frac{\partial}{\partial A} \int_A |\nabla C| dA \right]^2, \quad (22)$$

where $C$ is the tracer concentration and $A$ is the area between tracer contours.

REFERENCES


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