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# LATENT VARIABLE NONPARAMETRIC COINTEGRATING REGRESSION

By

Qiyang Wang, Peter C. B. Phillips, and Ioannis Kasparis

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YALE UNIVERSITY

Box 208281  
New Haven, Connecticut 06520-8281

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# Latent Variable Nonparametric Cointegrating Regression\*

Qiyang Wang<sup>†</sup>, Peter C. B. Phillips<sup>‡</sup> and Ioannis Kasparis<sup>§</sup>

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## Abstract

This paper studies the asymptotic properties of empirical nonparametric regressions that partially misspecify the relationships between nonstationary variables. In particular, we analyze nonparametric kernel regressions in which a potential nonlinear cointegrating regression is misspecified through the use of a proxy regressor in place of the true regressor. Such regressions arise naturally in linear and nonlinear regressions where the regressor suffers from measurement error or where the true regressor is a latent variable. The model considered allows for endogenous regressors as the latent variable and proxy variables that cointegrate asymptotically with the true latent variable. Such a framework includes correctly specified systems as well as misspecified models in which the actual regressor serves as a proxy variable for the true regressor. The system is therefore intermediate between nonlinear nonparametric cointegrating regression (Wang and Phillips, 2009a, 2009b) and completely misspecified nonparametric regressions in which the relationship is entirely spurious (Phillips, 2009). The asymptotic results relate to recent work on dynamic misspecification in nonparametric nonstationary systems by Kasparis and Phillips (2012) and Duffy (2014). The limit theory accommodates regressor variables with autoregressive roots that are local to unity and whose errors are driven by long memory and short memory innovations, thereby encompassing applications with a wide range of economic and financial time series.

*Keywords:* Cointegrating regression, Kernel regression, Latent variable, Local time, Misspecification, Nonlinear nonparametric nonstationary regression

*JEL classification:* C23

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<sup>†</sup>School of Mathematics and Statistics, The University of Sydney, NSW 2006, Australia, email: qiyang@maths.usyd.edu.au

<sup>‡</sup>University of Auckland, Auckland, New Zealand; Yale University, University of Southampton, Singapore Management University, email: peter.phillips@yale.edu.

<sup>§</sup>University of Cyprus, Nicosia, Cyprus, email: kasparis@ucy.ac.cy.

# 1 Introduction

Kernel regression methods are commonly used in empirical research when theory suggests no obvious model specification or when there is uncertainty about a given parametric specification and tests of that specification against a general nonparametric alternative may be desired. Time series models typically involve additional uncertainties about temporal dependence, nonstationarity, or memory properties of the variables in the regression. Such properties may be assessed by prior estimation or tests, but with the additional consequence of pre-test implications for inference. It is therefore desirable to have econometric methods of estimation and testing that accommodate a wide range of temporal dependence characteristics in the data. Recent research has shown that standard methods of nonparametric kernel regression may be conducted when the regressor has nonstationary characteristics of unknown and unspecified form, including autoregressive unit root, local unit root, or fractional unit root properties (Wang and Phillips, 2009a, 2009b, 2011, 2016 – hereafter WP; Duffy, 2014; Gao and Dong, 2017). In nonstationary cases an important aspect of this work is that the results apply even when the regressor is endogenous, thereby including nonparametric cointegrating regressions.

The present paper extends these results to include nonparametric cointegrating regressions in which the true regressor is a latent variable and a proxy variable is used in the empirical regression in place of the latent variable. Such regressions arise naturally when the true regressor is measured with error and/or when the proxy variable cointegrates asymptotically with the true latent variable. In this framework, the nonparametric nonstationary model suffers simultaneously from endogeneity of the latent regressor variable and measurement error in the observed proxy regressor. Such a framework is intermediate between correctly specified nonlinear nonparametric cointegrating regressions of the type studied in WP (2009a, 2009b) and completely spurious nonparametric regressions such as those in Phillips (2009). Important special cases of the present framework include nonparametric nonstationary systems in which the regressor is dynamically misspecified, as in the work by Kasparis and Phillips (2012), or similar nonstationary systems in which the true variable is measured with a stationary error, as in Duffy (2014).

The asymptotic results reveal the effects of misspecification, including the asymptotic bias, in nonparametric nonstationary regression. In certain cases such as when the true regression function is convex, the direction of the bias may be determined.<sup>1</sup> In general, when linkages between the observed regressor and the latent variable are ‘close’, in a sense that will be made precise, an empirical nonparametric regression has a clear interpretation in terms of its pseudo-true value limit as a local average of

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<sup>1</sup>In recent work on linear dynamic systems with nonstationary regressors Duffy and Hendry (2018) analyzed the effects of measurement error and were able to sign these effects in certain special cases.

the true cointegrating regression function. The findings of the paper therefore contribute in several ways to our present understanding of nonparametric cointegrating regression theory. They are particularly helpful in appreciating the combined impact of endogeneity and measurement error in such regressions.

The results of the paper also complement a large literature of recent microeconomic work on nonparametric estimation in the setting of an endogenous regressor and independently identically distributed (iid) data. In such models, instrumental variable methods and regularization techniques are used to overcome the inconsistency of standard nonparametric estimation by kernel or sieve methods (e.g., Hall and Horowitz, 2005; Horowitz, 2011; Chen and Reiss, 2011). When the explanatory variable suffers from measurement error, these methods are typically inconsistent even in the iid setting. Schennach (2004) studied such problems of nonparametric regression in the presence of measurement error, but without addressing endogeneity of the regressor. Most recently in this literature, Ausumilli and Otsu (2018) have developed wavelet basis methods for dealing simultaneously with an endogenous regressor that is measured with error, showing that the impact of measurement error is to reduce the (already slow) convergence rate of nonparametric IV estimation. The results of the present paper show that in the nonstationary time series setting under endogeneity and measurement error, the standard nonparametric kernel estimator is convergent at the usual rate but to a local average of the nonparametric cointegrating regression function.

The paper is organized as follows. Section 2 describes the latent variable nonparametric model of cointegration studied here. This model involves dual sources of endogeneity that arise from (i) the use of a proxy variable in the empirical regression, leading to measurement error, as well as (ii) inherent endogeneity in the regressor. Section 3 provides assumptions under which the asymptotics are developed and gives the limiting stochastic processes that are involved in the limit theory. Section 4 provides a general result on the limit behavior of sample nonlinear functionals, which extends many existing results on weak convergence to local time. This result is applied to deliver asymptotic results for sample covariance functionals that appear in latent variable nonparametric cointegrating regressions with a proxy variable regressor. Section 5 gives a law of large numbers and asymptotic distribution theory for such regressions, extending the limit theory in WP (2009b, 2016) for correctly specified cointegrated models to the latent variable case. Section 6 concludes. Proofs of the main results are given in Appendix A and supplementary results in Appendix B.

Throughout the paper, we make use of the following notation: for  $x = (x_1, \dots, x_d)$ ,  $\|x\| = \sum_{j=1}^d |x_j|$ . We denote constants by  $C, C_1, \dots$ , which may be different at each appearance.

## 2 Partially Misspecified Cointegrated Models

We suppose that two nonstationary variables  $(z_t, y_t)$  are linked according to the non-parametric regression model

$$z_t = m(y_t) + \eta_t, \quad t = 1, \dots, n \quad (2.1)$$

where  $m$  is an unknown function and  $\eta_t$  is a zero mean stationary disturbance whose properties are detailed below. In such models, it is natural to employ kernel regression methods to estimate the function  $m$ . When  $y_t$  is an integrated, near-integrated or fractionally integrated process, the model (2.1) is now commonly known as a nonlinear nonparametric cointegrating regression. The model may be estimated by kernel regression just as in stationary regression cases.

Importantly, and in contrast to stationary nonparametric regression, such kernel regression is consistent even when the regressor  $y_t$  is endogenous. The reason for this robustness to endogeneity in the regressor, as explained in WP (2009b), is that nonstationary regressors such as unit root processes have a wandering character that assists in tracing out the true regression function. In effect, a nonstationary regressor such as  $y_t$  serves as its own instrument in nonparametric kernel regression by delineating the shape of a smooth curve  $m$  as  $y$  varies over the entire real line by virtue of the recurrence of the limit process corresponding to a standardized version of  $y_t$ . This advantage might suggest that such nonparametric regressions might also show some degree of immunity even to measurement error in the regressor. However, Kasparis and Phillips (2012) discovered that this is not so by demonstrating that dynamic misspecification in the timing of the regressor dependence produces inconsistency in nonlinear nonparametric regressions, a result that differs markedly from parametric linear cointegrated regression where the dynamic timing of the regressor has no asymptotic import. Our following analysis reveals the effects of misspecification of a nonlinear regression function in a wide range of nonstationary cases that include measurement error in the regressor.

To fix ideas, we suppose that the regressor  $y_t$  in the true model (2.1) is latent and unavailable to the econometrician, whereas another variable  $x_t$  is observed and is used in the regression in place of  $y_t$ . The fitted nonparametric regression then has the form

$$z_t = \hat{m}(x_t) + \hat{\eta}_t, \quad (2.2)$$

where

$$\begin{aligned} \hat{m}(x) &= \frac{\sum_{t=1}^n z_t K[(x_t - x)/h]}{\sum_{t=1}^n K[(x_t - x)/h]} = \frac{\sum_{t=1}^n \eta_t K[(x_t - x)/h]}{\sum_{t=1}^n K[(x_t - x)/h]} + \frac{\sum_{t=1}^n m(y_t) K[(x_t - x)/h]}{\sum_{t=1}^n K[(x_t - x)/h]} \\ &=: \frac{P_n}{\sum_{t=1}^n K[(x_t - x)/h]} + \frac{S_n}{\sum_{t=1}^n K[(x_t - x)/h]}. \end{aligned} \quad (2.3)$$

We study the asymptotic behavior of the fitted nonparametric regression function  $\hat{m}(x)$  under certain regularity conditions that prescribe the relationship between  $x_t$  and the latent variable  $y_t$  and the generating mechanism of  $(x_t, y_t, \eta_t)$ . Analysis of (2.3) requires consideration of two components. The asymptotic behavior of the first component follows in much the same way as for a correctly specified system, which is given in WP (2009b). The second component embodies the effects of the misspecification in the numerator  $S_n$ . Its asymptotic behavior involves the study of sample covariances of the form

$$S_n = \sum_{t=1}^n m(y_t) K[(x_t - x)/h] = \sum_{t=1}^n m(y_t) K[\gamma_n(x_t - x)], \quad (2.4)$$

where  $\gamma_n = 1/h_n \rightarrow \infty$ , corresponding to a bandwidth sequence  $h = h_n \rightarrow 0$  as the sample size  $n \rightarrow \infty$ . Importantly, (2.4) depends on two nonstationary time series  $(y_t, x_t)$ , so that the limit theory for sample function  $S_n$  depends on any linkages involved in the generating mechanism of these two series. We now proceed to analyze sample functions involving such sample covariances of nonlinear functions of related nonstationary variables  $(y_t, x_t)$ . To begin, we define the conditions on these variables, the regression function in (2.1), and the properties of the errors  $\eta_t$ .

### 3 Assumptions and Preliminaries

Let  $\lambda_i = (\epsilon_i, e_i)$ ,  $i \in \mathbb{Z}$  be a sequence of iid random vectors with  $\mathbb{E}\lambda_0 = 0$ ,  $\mathbb{E}\|\lambda_0\|^2 < \infty$  and  $\lim_{|t| \rightarrow \infty} |t|^a [|\mathbb{E}e^{it\epsilon_0}| + |\mathbb{E}e^{ite_0}|] < \infty$  for some  $a > 0$ . The variates  $\lambda_i$  form primitive innovations in linear processes that are described below. We make use of the following assumptions about the components of (2.1) and (2.2) for the development of the asymptotic theory in our main results.

**A1.**  $x_k = \rho_n x_{k-1} + \xi_k$ , where  $\rho_n = 1 - \tau n^{-1}$  for some constant  $\tau \geq 0$ , and  $\xi_k = \sum_{j=0}^{\infty} \phi_j \epsilon_{k-j}$ . The coefficients  $\phi_k, k \geq 0$ , satisfy one of the following conditions:

*LM:*  $\phi_k \sim k^{-\mu} \rho(k)$ ,  $1/2 < \mu < 1$  and  $\rho(k)$  is a function slowly varying at  $\infty$ ;

*SM:*  $\sum_{k=0}^{\infty} |\phi_k| < \infty$  and  $\phi \equiv \sum_{k=0}^{\infty} \phi_k \neq 0$ .

**A2.** (i)  $u_k = \sum_{j=0}^{\infty} \psi_j \lambda'_{k-j}$  with  $\psi_j = (\psi_{1j}, \psi_{2j})$  satisfying  $\sum_{j=0}^{\infty} (|\psi_{1j}| + |\psi_{2j}|) < \infty$ ;  
(ii) The random array  $\{\nu_{nk}\}$  satisfies the bounding inequality  $|\nu_{nk}| \leq \delta_n \sum_{j=0}^{\infty} (|b_{1j} \epsilon_{k-j}| + |b_{2j} e_{k-j}|)$  where the coefficients  $b_j = (b_{1j}, b_{2j})$  themselves satisfy  $\sum_{j=0}^{\infty} (|b_{1j}| + |b_{2j}|) < \infty$  and the scalar sequence  $\delta_n \rightarrow 0$ , as  $n \rightarrow \infty$ .

**A3.**  $m(x, y)$  is a real function on  $\mathbb{R}^2$  satisfying the following conditions:

- (i)  $\mathbb{E}|m(t, u_1)|$ , where  $u_t$  is given in **A2**, is bounded and integrable;
- (ii) there exist  $\delta > 0$ , integers  $\alpha, \beta \geq 1$  and a bounded and integrable function  $T(x)$  such that, for all  $x, y, t \in \mathbb{R}$  and  $|\gamma| \leq 1$ ,

$$|m(x, y + \gamma t) - m(x, y)| \leq \gamma^\delta (1 + |t|^\alpha) (1 + |y|^\beta) T(x). \quad (3.5)$$

Assumption **A1** allows for nearly integrated autoregressive transforms of short and long memory linear processes, a general linear process set up that has been widely used in the nonparametric nonstationary time series literature – see WP (2009a, b, 2011, 2016) and Wang (2014, 2015). Assumption **A2** ensures that  $u_k$  is a stationary linear process and  $\nu_{nk}$  is an asymptotically negligible random component that plays a role in bounding one of the components of the misspecification error in our main result. By virtue of the boundedness and integrability requirement of  $\mathbb{E}|m(t, u_1)|$  given in **A3** (i) there exists a finite constant  $c_0$  such that the function  $m(t, c_0)$  is bounded and integrable. This fact will be used in the proofs that follow without further reference.

Assumption **A3** (ii) is a weak condition of uniform continuity for multi-argument functions. It is easy to verify in applications. To give an illustration, we introduce the following simpler condition **A4**.

- A4** (i) For some given function  $f$ , there exist  $\delta > 0$  and integers  $\alpha, \beta \geq 1$  such that, for all  $y, t \in \mathbb{R}$  and  $|\gamma| \leq 1$ ,

$$|f(y + \gamma t) - f(y)| \leq C \gamma^\delta (1 + |t|^\alpha) (1 + |y|^\beta); \quad (3.6)$$

- (ii)  $\int_{-\infty}^{\infty} K(x) dx = 1$  and  $(1 + |x|^{\alpha+\beta})K(x)$  is bounded and integrable, where  $\alpha, \beta$  are given in (3.6).

It is readily seen that functions such as  $f(y) = |y|^\alpha, 1/(1 + |y|^\alpha)$  satisfy (3.6). Then, if  $K(x)$  and  $f(y)$  satisfy **A4**, it follows that

$$m(x, y) = K(x) f(x + y) \quad \text{and} \quad K(x) f(y) \quad (3.7)$$

satisfy (3.5). As will become apparent in what follows, the role of the function  $m(x, y)$  in applications is to provide a linkage between the observable time series  $x_t$  and the latent variable  $y_t$  in the model (2.1) and fitted regression (2.2). This linkage function allows for potential cointegrating links between  $y_t$  and  $x_t$  as well as measurement error. Corollary 4.1 below details a typical linkage function of this type and shows how the limit theory of sample covariance functionals of two nonstationary time series that is given in our Theorem 4.1 can be applied to analyze misspecification components such as those arising from the second term in (2.3).

To complete this section, we define some stochastic processes that appear in the limit theory. In the following, let  $d_n^2 = \text{var}(\sum_{j=1}^n \xi_j)$  and, for  $t \geq 0$ , define the



continuous stochastic processes

$$Z_t = W(t) + \tau \int_0^t e^{-\tau(t-s)} W(s) ds,$$

$$W(t) = \begin{cases} B_{3/2-u}(t), & \text{under } \mathbf{LM}, \\ B_{1/2}(t), & \text{under } \mathbf{SM}, \end{cases}$$

where  $B_H(t)$  is fractional Brownian motion with Hurst exponent  $H$ . In this event, it is well known that  $Z_t$  is a fractional Ornstein-Uhlenbeck process, having continuous local time which we denote by  $L_Z(t, x)$ . We further have the following asymptotic orders

$$(\mathbb{E}\epsilon_0^2)^{-1} d_n^2 \sim \begin{cases} c_\mu n^{3-2\mu} \rho^2(n), & \text{under } \mathbf{LM}, \\ \phi^2 n, & \text{under } \mathbf{SM}, \end{cases}$$

where  $c_\mu = \frac{1}{(1-\mu)(3-2\mu)} \int_0^\infty x^{-\mu}(x+1)^{-\mu} dx$  (e.g., see Giraitis et al., 2012, or Wang et al., 2003). Finally, it is known (Jeganathan, 2008; WP, 2009a) that the functional law  $Z_{n\lfloor nt \rfloor} \Rightarrow Z_t$  holds in the Skorohod space  $D[0, 1]$  for the standardized element  $Z_{nk} = x_k/d_n$  where  $k = \lfloor nt \rfloor$  is the integer part of  $nt$ .

## 4 Sample Limit Theory for Nonlinear Functionals

Our first main result concerns the limit behavior of a standardized sample mean functional of a nonlinear function with multiple arguments that involve stationary and nonstationary processes. Such functionals turn out to be very useful in determining asymptotics for sample covariance functionals such as (2.4) that appear in misspecified fitted nonparametric regressions like (2.2). The following result is given in a general form to enhance its usefulness both in the present context and other applications.

**Theorem 4.1.** *In addition to **A1–A3**, suppose that  $\mathbb{E}||\lambda_0||^{\max\{2\alpha, \alpha+\beta\}} < \infty$  where  $\alpha$  and  $\beta$  are given as in (3.5) of **A3**. For any  $c_n \rightarrow \infty$  with  $c_n/n \rightarrow 0$  and  $z \in \mathbb{R}$ , we have*

$$\frac{c_n}{n} \sum_{t=1}^n m[c_n(Z_{nt} + c'_n z), u_t + \nu_{nt}] \rightarrow_D \int_{-\infty}^{\infty} m_1(t) dt \tilde{L}_Z(1, z), \quad (4.8)$$

where  $Z_{nk} = x_k/d_n$ ,  $m_1(t) = \mathbb{E}m(t, u_1)$  and

$$\tilde{L}_Z(r, z) = \begin{cases} L_Z(r, 0), & \text{if } c'_n \rightarrow 0, \\ L_Z(r, -z), & \text{if } c'_n = 1. \end{cases}$$

**Remark 1.** An important element of the proof of Theorem 4.1 involves demonstrating that the sample mean functional can be asymptotically approximated so that the residual difference

$$R_n := \frac{c_n}{n} \sum_{t=1}^n \left[ m(c_n Z_{nt}, u_t + \nu_{nt}) - m_1(c_n Z_{nt}) \right] = o_P(1). \quad (4.9)$$

The rate at which  $R_n$  converges to zero heavily depends on the sequence  $\delta_n$  given in **A2** (ii). Indeed, by letting  $m(x, y) = K(x)y$ , where  $\nu_{nt} = \delta_n |\epsilon_t|$  and  $K$  satisfies certain smoothness conditions, as in Proposition 7.2 of WP (2016), it is readily seen that

$$R_n = \frac{c_n}{n} \sum_{t=1}^n K(c_n Z_{nt}) (u_t + \delta_n |\epsilon_t|) = O_P(\delta_n).$$

This rate cannot be improved. The representation (4.9) suggests that the existence of a limit distribution for the sample mean functional in (4.8), and hence that of a suitably standardized version of (2.4), relies on the validity of an asymptotic approximation of the form (4.9). Indeed, it seems unrealistic to consider the asymptotic distribution of sample functionals such as (4.8), at least in this framework, except in cases where the approximating residual element  $R_n$  has the property that  $\nu_{nt} \rightarrow_P 0$  so that (4.9) holds with some convergence rate. In some specialized cases of the latter situation, the asymptotic behavior of  $R_n$  is known and has been considered in WP (2016) and Duffy (2014) for some particular functions  $m(x, y)$ , specifically  $m(x, y) = K(x)y$ . It would be interesting to consider more general extensions of this framework in which residual elements such as  $R_n$  do not necessarily have the property that  $\nu_{nt} \rightarrow_P 0$  and where the approximating component is not necessarily of the form  $m_1$ . Such extensions would assist in analyzing spurious nonparametric regressions with nonstationary series, which have been considered in a special case by Phillips (2009), as discussed below. But such an extension seems beyond the scope of our present methods and is therefore left as a challenge for future work.

**Remark 2.** In spite of this limitation, Theorem 4.1 still provides a very general extension of existing results on convergence of sample functions to quantities that involve scaled local time, as is apparent from the form of (4.8). In previous research, WP (2009a, 2009b) [see also Jeganathan (2008) and Chapter 1 of Wang (2015)] established similar results for the statistic  $\frac{c_n}{n} \sum_{t=1}^n K[c_n(Z_{nt} + c'_n z)] m(\lambda_t, \dots, \lambda_{t-m_0})$ , where  $m_0$  is a fixed constant. Moving toward a general formulation of  $m(x, y)$ , for  $x_t$  satisfying **A1** with  $\tau = 0$  and the coefficients  $\phi_k$  satisfying the *SM* condition, Duffy (2014) provided a result for  $n^{-1/2} \sum_{t=1}^n m(x_k, u_k)$  under a strong smoothness condition on  $m(x, y)$ . Our Theorem 4.1 has the advantage that it allows for nearly integrated long memory as well as short memory linear processes, which are now widely used in the applied literature, in addition to processes that satisfy some general linkage relationships, as will be apparent in our applications below. Furthermore, our formulation of  $m(x, y)$

enables easy implementation of Theorem 4.1 to several useful practical applications, as is indicated in the following corollaries.

**Corollary 4.1.** *Let  $y_k = \alpha_{nk} x_k + \nu_{nk} + u_k$ , where  $\max_{1 \leq k \leq n} |\alpha_{nk} - \alpha_0| \rightarrow 0$ , as  $n \rightarrow \infty$ , for some  $\alpha_0 \in \mathbb{R}$ . If, in addition **A1**, **A2** and **A4**,  $\mathbb{E} \|\lambda_0\|^{\max\{2\alpha, \alpha+\beta\}} < \infty$  where  $\alpha$  and  $\beta$  are given as in (3.6). Then, for any fixed  $x \in \mathbb{R}$ ,*

$$\frac{d_n}{nh} \sum_{t=1}^n f(y_t) K[(x_t - x)/h] \rightarrow_D \mathbb{E} f(\alpha_0 x + u_1) L_Z(1, 0), \quad (4.10)$$

whenever  $h := h_n \rightarrow 0$  and  $d_n/nh \rightarrow 0$ . When  $h = 1$ , we have

$$\frac{d_n}{n} \sum_{t=1}^n f(y_t) K(x_t - x) \rightarrow_D \int_{-\infty}^{\infty} \mathbb{E} f(\alpha_0 t + \alpha_0 x + u_1) K(t) dt L_Z(1, 0). \quad (4.11)$$

**Remark 3.** Phillips (2009) gave the first investigation of asymptotics for sample covariance functionals of the form  $\sum_{t=1}^n f(y_t) K[(x_t - x)/h]$  where both  $x_t$  and  $y_t$  are  $I(1)$  processes. The argument in that work essentially imposed independence between the time series  $x_t$  and  $y_t$  so that there was no linkage at all between the variables, thereby extending the standard spurious linear regression framework (Phillips, 1986; Granger and Newbold, 1974) to nonparametric regression. The limit distribution in that spurious nonparametric regression framework for  $x_t$  and  $y_t$  differs from Corollary 4.1 in this paper where there is an explicit linkage between the variables. In particular, the situation considered here is that  $y_t$  is “close” to being linearly cointegrated with  $x_t$  with an asymptotically constant coefficient and a stationary shift subject to an asymptotically negligible error. This present framework corresponds to the replacement of a latent variable  $y_t$  in a nonparametric regression with a proxy variable  $x_t$  whose long term properties are closely related but are measured with error. In this setting, the limit distribution given in (4.11) still involves the local time of the Gaussian process  $Z_t$  associated with the weak limit of the process  $Z_{n[nt]}$  based on standardized versions of the sample observations  $x_{[nt]}$ . It is not clear at the moment if more general versions of a spurious regression type of result exist under the same setting of Phillips (2009) but without imposing independence between  $x_t$  and  $y_t$ .

**Remark 4.** Kasparis and Phillips (2012) investigated the asymptotics of  $S_n := \sum_{t=1}^n f(x_{t+d}) K[(x_t - x)/h]$  under certain strict conditions on  $x_t$ , essentially requiring  $x_t$  to be a random walk with iid innovations. As a direct consequence of Theorem 4.1, we may establish similar results under less restrictive conditions. To illustrate, for some  $d \geq 1$ , let

$$y_k = \sum_{j=-d}^d \alpha_{nk}(j) x_{k+j}, \quad \text{where } \max_{\substack{1 \leq k \leq n \\ -d \leq j \leq d}} |\alpha_{nk}(j) - \alpha_j| \rightarrow 0. \quad (4.12)$$

Note that, for any  $j \geq 1$ ,

$$\begin{aligned} x_{k+j} &= \rho_n x_{k+j-1} + \xi_{t+j} = \dots = \rho_n^j x_k + \sum_{i=1}^j \rho_n^{j-i} \xi_{k+i}, \\ x_{k-j} &= \rho_n^{-1} x_{k-j+1} - \rho_n^{-1} \xi_{k-j+1} = \dots = \rho_n^{-j} x_k - \sum_{i=0}^{j-1} \rho_n^{-j+i} \xi_{k-i}. \end{aligned}$$

We may therefore write

$$\begin{aligned} y_k &= x_k \sum_{j=-d}^d \alpha_{nk}(j) \rho_n^j + \sum_{j=1}^d \alpha_{nk}(j) \sum_{i=1}^j \rho_n^{j-i} \xi_{k+i} - \sum_{j=1}^d \alpha_{nk}(-j) \sum_{i=0}^{j-1} \rho_n^{-j+i} \xi_{k-i} \\ &= x_k \sum_{j=-d}^d \alpha_{nk}(j) \rho_n^j + \sum_{i=1}^d \xi_{k+i} \sum_{j=i}^d \alpha_{nk}(j) \rho_n^{j-i} - \sum_{i=1}^d \xi_{k-i+1} \sum_{j=i}^d \alpha_{nk}(-j) \rho_n^{-j+i-1} \\ &= x_k \alpha_{nk}^* + \nu_{nk} + u_k, \end{aligned} \tag{4.13}$$

where, by letting  $\delta_n = \max_{\substack{1 \leq k \leq n \\ -d \leq j \leq d}} |\alpha_{nk}(j) - \alpha_j| + \max_{-d \leq j \leq d} |\rho_n^j - 1|$ , we have

$$\begin{aligned} \alpha_{nk}^* &= \sum_{j=-d}^d \alpha_{nk}(j) \rho_n^j = \sum_{j=-d}^d \alpha_j + O(\delta_n), \\ u_k &= \sum_{i=1}^d \xi_{k+i} \sum_{j=i}^d \alpha_j - \sum_{i=1}^d \xi_{k-i+1} \sum_{j=i}^d \alpha_{-j}, \end{aligned}$$

and

$$\begin{aligned} |\nu_{nk}| &\leq \sum_{i=1}^d |\xi_{k+i}| \sum_{j=i}^d |\alpha_{nk}(j) \rho_n^{j-i} - \alpha_j| \\ &\quad + \sum_{i=1}^d |\xi_{k-i+1}| \sum_{j=i}^d |\alpha_{nk}(-j) \rho_n^{-j+i-1} - \alpha_{-j}| \\ &\leq C \delta_n \sum_{i=1}^d (|\xi_{k+i}| + |\xi_{k-i+1}|). \end{aligned}$$

Now suppose that  $\xi_t = \sum_{j=0}^{\infty} \phi_j \epsilon_{t-j}$  with  $\sum_{j=0}^{\infty} |\phi_j| < \infty$  and  $\phi = \sum_{j=0}^{\infty} \phi_j \neq 0$ , so that  $x_t$  satisfies **A1** with *SM* memory. Since  $\delta_n \rightarrow 0$ , it is readily seen from (4.13) that  $\nu_{nt}$  and  $u_t$  given in (4.12) satisfy **A2**. As an immediate consequence of Corollary 4.1, we have the following result.

**Corollary 4.2.** *Suppose that **A1** with coefficients satisfying *SM* holds. Suppose also that **A4** holds and  $\mathbb{E} \|\lambda_0\|^{\max\{2\alpha, \alpha+\beta\}} < \infty$ , where  $\alpha$  and  $\beta$  are given as in (3.6). Then,*

for any fixed  $x \in \mathbb{R}$  and  $y_t$  defined in (4.12),

$$\begin{aligned} & \frac{1}{\sqrt{nh}} \sum_{t=1}^n f(y_t) K[(x_t - x)/h] \\ \rightarrow_D & \phi^{-1}(\mathbb{E}\epsilon_0^2)^{-1/2} \mathbb{E}f\left(x \sum_{j=-d}^d \alpha_j + \sum_{i=1}^d \xi_i \sum_{j=i}^d \alpha_j - \sum_{i=1}^d \xi_{-i+1} \sum_{j=i}^d \alpha_{-j}\right) \\ & \times L_Z(1, 0), \end{aligned} \tag{4.14}$$

whenever  $h \rightarrow 0$  and  $n^2h \rightarrow \infty$ . In particular, we have

$$\begin{aligned} & \frac{1}{\sqrt{nh}} \sum_{t=d}^n f(x_t) K\left(\frac{x_{t-d} - x}{h}\right) \rightarrow_D \frac{1}{\phi(\mathbb{E}\epsilon_0^2)^{1/2}} \mathbb{E}\left\{f\left(x + \sum_{j=1}^d \xi_j\right)\right\} L_Z(1, 0), \\ & \frac{1}{\sqrt{nh}} \sum_{t=d}^n f(x_{t-d}) K\left(\frac{x_{t-d} - x}{h}\right) \rightarrow_D \frac{1}{\phi(\mathbb{E}\epsilon_0^2)^{1/2}} \mathbb{E}\left\{f\left(x - \sum_{j=1}^d \xi_j\right)\right\} L_Z(1, 0). \end{aligned}$$

Using (4.11), results for  $h = 1$  can be derived similarly. The details are omitted.

## 5 Applications

This section develops a nonparametric regression application of our limit theory for sample covariance functionals of nonstationary time series. Except where mentioned explicitly, the notation used here is the same as in Sections 2-3.

Suppose that the time series  $(z_t, x_t)$  are observed but the real data generating process has the form

$$z_t = g(y_t) + \eta_t, \quad y_t = \alpha_{nt} x_t + \nu_{nt} + u_t, \tag{5.15}$$

where  $g(x)$  is an unknown regression function,  $x_t, u_t$  and  $\nu_{nt}$  satisfy **A1** and **A2**, and  $\eta_t$  is an error process defined by

$$\eta_t = \sum_{j=0}^{\infty} \theta_j \lambda'_{t-j}$$

with  $\theta_j = (\theta_{1j}, \theta_{2j})$  satisfying  $\sum_{j=0}^{\infty} j^{1/4} (|\theta_{1j}| + |\theta_{2j}|) < \infty$ . We further assume that

$$\beta_n := \max_{1 \leq k \leq n} |\alpha_{nk} - 1| \rightarrow 0. \quad \text{as } n \rightarrow \infty,$$

This formulation involves a nonparametric regression model with latent endogenous regressor variable  $y_t$  that is observed with error via a proxy variable  $x_t$  that is asymptotically linked through an approximate cointegrating relation to  $y_t$ . The resulting

fitted regression is a partially misspecified nonlinear nonparametric cointegrating regression.

Since data on only  $(z_t, x_t)$  is observed, standard kernel estimation of the function  $g$  leads to

$$\hat{g}(x) = \frac{\sum z_t K[(x_t - x)/h]}{\sum K[(x_t - x)/h]},$$

where  $K$  is a non-negative kernel function and the bandwidth  $h := h_n \rightarrow 0$ . The following result shows the limit behavior of  $\hat{g}(x)$ .

**Theorem 5.1.** *If, when  $f(x)$  is replaced by  $g(x)$ , **A4** holds and  $\mathbb{E}||\lambda_0||^{\max\{2\alpha, \alpha+\beta\}} < \infty$  where  $\alpha$  and  $\beta$  are given in **A4**, then*

$$\hat{g}(x) \rightarrow_P g_1(x) := \mathbb{E}g(x + u_1), \quad (5.16)$$

for any fixed  $x$  and  $h \rightarrow 0$  satisfying  $d_n/nh \rightarrow 0$ .

**Remark 5.** Since, in general,  $g_1(x) \neq g(x)$ , the nonparametric estimate  $\hat{g}(x)$  will usually produce an inconsistent estimate of  $g(x)$ . Moreover, if  $g(x)$  is sufficiently smooth so that  $g''(t) \geq 0$  for any  $t \in \mathbb{R}$ <sup>2</sup>, we have  $g_1(x) \geq g(x)$ , indicating a positive bias in this misspecified nonparametric regression. When  $g$  is linear,  $g_1(x) = g(x)$  and  $\hat{g}(x)$  is consistent, just as in linear cointegrating regression with stationary measurement error. When  $g$  is nonlinear, the limit expression (5.16) is still informative. In this case the pseudo true regression function  $g_1(x) = \mathbb{E}g(x + u_1)$  represents a local average value of  $g$  around its value at  $x$  where the weighted average is taken with respect to the density of the measurement error  $u$  in (5.15). The nature of the asymptotic bias  $g_1(x) - g(x)$  then depends on the degree of nonlinearity of  $g$  in conjunction with the shape and support of the density of the measurement error.

**Remark 6.** Under somewhat stronger conditions on  $g(x)$ ,  $u_t$ ,  $\alpha_{nk}$  and  $\delta_n$ , it is possible to establish the asymptotic distribution of  $R_n(x) := \hat{g}(x) - g_1(x)$ . Indeed, we may establish Theorem 3.2 below by making use of the following assumption.

**A5.** (i) For some integer  $\beta \geq 1$ , when  $x, y \in \mathbb{R}$  and  $t$  is sufficiently small, we have

$$|g(x + ty) - g(x)| \leq C|t|(1 + |x|^\beta)(1 + |y|);$$

(ii)  $\int_{-\infty}^{\infty} K(x)dx = 1$  and  $K(x)$  has a finite compact support;

(iii)  $x_t$  is defined as in **A1** and  $u_k = \sum_{j=0}^{\infty} \psi_j \lambda'_{k-j}$ , where the coefficients  $\psi_j = (\psi_{1j}, \psi_{2j})$  satisfy that  $\sum_{j=0}^{\infty} \|\psi_j\| < \infty$  and  $n \sum_{j=\nu_n}^{\infty} \|\psi_j\|^2 = o(1)$  with  $\nu_n = (n/d_n)^\delta$  for some  $\delta < 1/3$ ;

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<sup>2</sup>Taylor expansion yields  $g(x + u_1) = g(x) + g'(x)u_1 + \frac{1}{2}g''(\xi)u_1^2$  for some  $\xi$  between  $x$  and  $x + u_1$ , and the claim follows from  $g''(\xi) \geq 0$ ,  $Eu_1 = 0$  and  $Eu_1^2 > 0$ .

- (iv)  $nh/d_n \rightarrow \infty$ ,  $nh^3/d_n \rightarrow 0$  and  $\beta_n + \delta_n = O(h)$ ;
- (v)  $E||\lambda_1||^{2\beta} < \infty$ .

**Theorem 5.2.** *Under **A5**, for any fixed  $x$ , we have*

$$\left( \sum_{k=1}^n K[(x_k - x)/h] \right)^{1/2} [\hat{g}(x) - g_1(x)] \rightarrow_D \Lambda N(0, 1), \quad (5.17)$$

where  $\Lambda^2 = E[\eta_1 + g(x + u_1) - g_1(x)]^2 \int_{-\infty}^{\infty} K^2(y) dy$ .

**Remark 7.** WP (2016) established (5.17) without investigating the effect of misspecification in the model, thereby imposing the conditions that  $u_t = \nu_{nt} = 0$ , and  $\alpha_{nk} = 1$  on the present framework. Duffy (2014) allowed for  $u_t \neq 0$ , while still imposing  $\nu_{nt} = 0$  and  $\alpha_{nk} = 1$ , but requiring  $\tau = 0$  for the time series  $x_t$  defined in **A1** and requiring the coefficients  $\phi_k$  to have *SM* memory, thereby restricting attention to  $I(1)$  time series. Our Theorem 5.2 provides a general result for nonparametric regression under misspecification that allows for nearly integrated short and long memory latent variables that are observed with error. This result substantially extends the existing literature on nonparametric nonstationary regression to a latent variable framework that covers many potential time series applications in econometric work in which measurement error effects may be expected.

## 6 Conclusion

The present framework focuses on latent variable nonparametric cointegrating regressions which are partially misspecified through the presence of measurement error or the use of proxy variables in the regression. The limit theory reveals that such regressions lead to bias in estimation yet may be interpreted as estimating locally weighted averages of the true regression function and are amenable to inference. The latent variable framework does not include fully spurious nonparametric regression systems of the type studied in Phillips (2009). Extensions to such systems are of interest not only from the perspective of completing the limit theory for linear spurious regression (Phillips, 1986) to include nonlinear nonparametric regression but also because the present results seem close to the limit of what is possible for partially misspecified regressions arising from latent variable measurement error. It is therefore of interest to understand how gross misspecification, as distinct from partial misspecification due to measurement error, affects such regressions with randomly trending variables.

Nonparametric regressions offer empirical researchers considerably more flexibility than linear regressions in establishing ‘empirical relationships’. Given the well-known tendency of trending variables to produce plausible regression findings in the absence

of an underlying relationship between the variables, it is important to understand the implications of conducting nonparametric regressions with such variables when the linkages between the variables are no longer as ‘close’ as the partially misspecified linkages studied in the present paper. What the present paper does show is that when there are ‘close’ linkages between the observed regressor and the latent variable, an empirical nonparametric regression has a clear interpretation in terms of a local average relationship of the true regression function. In this sense, there is useful interpretable information that can be recovered from the pseudo-true value in nonparametric nonstationary regression with latent variables.

## 7 Appendix A: Proofs of the main results

We first introduce two lemmas that play a key role in the proofs of our main results. Notation is the same as in previous sections except where explicitly mentioned.

**Lemma 7.1.** *Let  $p(x, x_1, \dots, x_m)$  be a real function of its components and  $t_1, \dots, t_m \in \mathbb{Z}$ , where  $m \geq 0$ . There exists an  $m_0 > 0$  such that the following results hold.*

(i) *For any  $h > 0$  and  $k \geq 2m + m_0$ , we have*

$$\mathbb{E}|p(x_k/h, \lambda_{t_1}, \dots, \lambda_{t_m})| \leq \frac{C h}{d_k} \int_{-\infty}^{\infty} \mathbb{E}|p(t, \lambda_1, \dots, \lambda_m)| dt. \quad (7.18)$$

(ii) *For any  $h > 0$ ,  $k - j \geq 2m + m_0$  and  $j + 1 \leq t_1, \dots, t_m \leq k$ , we have*

$$\mathbb{E}[|p(x_k/h, \lambda_{t_1}, \dots, \lambda_{t_m})| \mid \mathcal{F}_j] \leq \frac{C h}{d_{k-j}} \int_{-\infty}^{\infty} \mathbb{E}|p(t, \lambda_1, \dots, \lambda_m)| dt. \quad (7.19)$$

(iii) *If in addition  $\mathbb{E}p(t, \lambda_1, \dots, \lambda_m) = 0$  for any  $t \in \mathbb{R}$ , then*

$$\begin{aligned} & |\mathbb{E}[p(x_k/h, \lambda_{t_1}, \dots, \lambda_{t_m}) \mid \mathcal{F}_j]| \\ & \leq \frac{C h \sum_{j=0}^{k-\min\{t_1, \dots, t_m\}} |\phi_j|}{d_{k-j}^2} \int_{-\infty}^{\infty} \mathbb{E}\left\{|p(y, \lambda_1, \dots, \lambda_m)| \sum_{j=1}^m |\epsilon_j|\right\} dy. \end{aligned} \quad (7.20)$$

The proof of Lemma 7.1 is similar to Lemma 2.1 of Wang (2015). See, also, Lemma 8.1 of Wang and Phillips (2016). A proof of (7.20) is given in Appendix B for convenience. Note that, for any  $a_k, b_k$  and  $m \geq 1$ ,

$$\left(\sum_{k=0}^{\infty} |a_k b_k|\right)^m \leq \left(\sum_{k=0}^{\infty} |a_k|\right)^{m-1} \sum_{k=0}^{\infty} |a_k| |b_k|^m, \quad (7.21)$$

by Hölder’s inequality. A simple application of (7.18) yields that



(i) if  $\mathbb{E}||\lambda_1||^m < \infty$ , then

$$\sum_{t=1}^n (1 + |w_{nt}|^m) p(x_t/h) = O_P(nh/d_n); \quad (7.22)$$

(ii) if  $\mathbb{E}||\lambda_1||^{m+1} < \infty$ , then

$$\sum_{t=1}^n ||\lambda_{t-j}|| (1 + |w_{nt}|^m) p(x_t/h) = O_P(nh/d_n), \quad (7.23)$$

for any  $h > 0$  and  $j \in \mathbb{Z}$ , where  $p(x)$  is a bounded integrable function and  $w_{nt} = \sum_{k=0}^{\infty} c_{nk} \lambda'_{t-k}$  with  $c_{nk} = (c_{n,1k}, c_{n,2k})$  satisfying

$$\sup_{n \geq 1} \sum_{k=0}^{\infty} (|c_{n,1k}| + |c_{n,2k}|) < \infty.$$

Results (7.22) and (7.23) will be directly used in the following proofs without further explanation.

**Lemma 7.2.** *If, in addition to **A5**,  $\mathbb{E}g(u_1) = 0$ , then*

$$\begin{aligned} & \frac{d_n}{nh} \sum_{t=1}^n K[(x_t - x)/h], \left(\frac{d_n}{nh}\right)^{1/2} \sum_{t=1}^n [\eta_t + g(u_t)] K[(x_t - x)/h] \\ \rightarrow_D & (L_Z(1, 0), a_0 N \times L_Z(1, 0)^{1/2}), \end{aligned} \quad (7.24)$$

where  $a_0^2 = \mathbb{E}[\eta_1 + g(u_1)]^2$  and  $N \sim N(0, 1)$  independent of  $L_Z(1, 0)$ .

*Proof.* For any  $m > 0$ , let  $u_{mt} = \sum_{j=0}^m \psi_j \lambda'_{t-j}$  and  $\eta_{mt} = \sum_{j=0}^m \theta_j \lambda'_{t-j}$ . By noting  $Eg(u_t) = Eg(u_1) = 0$ , we may write

$$\begin{aligned} & \sum_{t=1}^n [\eta_t + g(u_t)] K[(x_t - x)/h] \\ = & \sum_{t=1}^n [\eta_{mt} + g(u_{mt}) - \mathbb{E}g(u_{mt})] K[(x_t - x)/h] + R_{n1} + R_{n2} \end{aligned}$$

where  $R_{n1} = \sum_{t=1}^n (\eta_t - \eta_{mt}) K[(x_t - x)/h]$  and

$$R_{n2} = \sum_{t=1}^n \{g(u_t) - g(u_{mt}) - \mathbb{E}[g(u_t) - g(u_{mt})]\} K[(x_t - x)/h].$$

For any  $m > 0$ , it follows from Wang and Phillips (2009a, 2009b) that

$$\begin{aligned} & \left(\frac{d_n}{nh} \sum_{t=1}^n K[(x_t - x)/h], \left(\frac{d_n}{nh}\right)^{1/2} \sum_{t=1}^n [\eta_{mt} + g(u_{mt}) - \mathbb{E}g(u_{mt})] K[(x_t - x)/h]\right) \\ \rightarrow_D & (L_Z(1, 0), a_m N \times L_Z(1, 0)^{1/2}), \end{aligned} \quad (7.25)$$

where  $a_m^2 = \mathbb{E}[\eta_{m1} + g(u_{m1}) - \mathbb{E}g(u_{m1})]^2$ . Result (7.24) will follow if we prove

$$a_m^2 \rightarrow a_0^2, \quad (7.26)$$

as  $m \rightarrow \infty$ , and, for  $i = 1$  and  $2$ ,

$$R_{ni} = o_p[(nh/d_n)^{1/2}], \quad (7.27)$$

as  $n \rightarrow \infty$  first and then  $m \rightarrow \infty$ .

We only prove (7.27) for  $i = 2$ . The proof of (7.27) for  $i = 1$  is similar [see, (8.13) of Wang and Phillips (2016), for instance]. Due to **A5** and  $\mathbb{E}g(u_1) = 0$ , the proof of (7.26) is trivial. We omit the details. To prove (7.27) for  $i = 2$ , we write

$$R_{n2} = R_{n3} + R_{n4}, \quad (7.28)$$

where, for  $\nu_n$  given in **A5** (iii),

$$\begin{aligned} R_{n3} &= \sum_{t=1}^n \{g(u_t) - g(u_{\nu_n t}) - \mathbb{E}[g(u_t) - g(u_{\nu_n t})]\} K[(x_t - x)/h] \\ R_{n4} &= \sum_{t=1}^n \{g(u_{\nu_n t}) - g(u_{mt}) - \mathbb{E}[g(u_{\nu_n t}) - g(u_{mt})]\} K[(x_t - x)/h] \end{aligned}$$

Note that  $u_t - u_{\nu_n t} = \sum_{j=\nu_n+1}^{\infty} \psi_j \lambda'_{t-j}$ . By using **A5** and (7.22) with  $m = 2\beta$ , it follows from the Hölder's inequality that

$$\begin{aligned} |R_{n3}| &\leq C \sum_{t=1}^n |u_t - u_{\nu_n t}| (1 + |u_{\nu_n t}|^\beta) K[(x_t - x)/h] \\ &\quad + C \sum_{t=1}^n \mathbb{E}\{|u_t - u_{\nu_n t}| (1 + |u_{\nu_n t}|^\beta)\} K[(x_t - x)/h] \\ &\leq C \left( \sum_{t=1}^n |u_t - u_{\nu_n t}|^2 \right)^{1/2} \left\{ \sum_{t=1}^n (1 + |u_{\nu_n t}|^{2\beta}) K^2[(x_t - x)/h] \right\}^{1/2} \\ &\quad + C \left( \sum_{j=\nu_n}^{\infty} \|\psi_j\|^2 \right)^{1/2} \sum_{t=1}^n K[(x_t - x)/h] \\ &= O_P \left\{ \left( n \sum_{j=\nu_n}^{\infty} \|\psi_j\|^2 \right)^{1/2} [(nh/d_n)^{1/2} + n^{-1/2}(nh/d_n)] \right\} \\ &= o_P[(nh/d_n)^{1/2}]. \end{aligned}$$

Taking this into (7.28), to prove (7.27) for  $i = 2$ , it suffices to show that

$$R_{n4} = o_P[(nh/d_n)^{1/2}], \quad (7.29)$$

as  $n \rightarrow \infty$  first and then  $m \rightarrow \infty$ .

To prove (7.29), let  $g_t = g(u_{\nu_n t}) - g(u_{mt}) - E[g(u_{\nu_n t}) - g(u_{mt})]$  and  $\nu_{1n} = 2\nu_n + m_0$ , where  $m_0$  is defined as in Lemma 7.1. We may write

$$R_{n4} = \left( \sum_{t=1}^{\nu_{1n}} + \sum_{t=\nu_{1n}+1}^n \right) g_t K[(x_t - x)/h] := R_{n5} + R_{n6}. \quad (7.30)$$

It is readily seen that, by recalling  $\nu_n = (n/d_n)^\delta$  for some  $\delta < 1/3$  and  $|g_t| \leq C \sum_{j=m}^\infty |\psi_j \lambda'_{t-j}| (1 + |u_{mt}|^\beta)$  by **A5(i)**,

$$|R_{n5}| \leq C \sum_{t=1}^{\nu_{1n}} |g_t| K[(x_t - x)/h] = O_P(\nu_n h / d_{\nu_n}) = o_P[(nh/d_n)^{1/2}]. \quad (7.31)$$

As for  $R_{n6}$ , we have

$$\begin{aligned} \mathbb{E} R_{n6}^2 &= \sum_{s,t=\nu_{1n}+1}^n \mathbb{E} \left\{ g_s g_t K[(x_s - x)/h] K[(x_t - x)/h] \right\} \\ &= 2 \sum_{t=\nu_{1n}+1}^n \left( \sum_{s=0}^{m_0} + \sum_{s=m_0+1}^{\nu_{1n}} + \sum_{s=\nu_{1n}+1}^{n-t} \right) \mathbb{E} \left\{ g_t g_{t+s} K[(x_t - x)/h] K[(x_{t+s} - x)/h] \right\} \\ &:= \Delta_{1n} + \Delta_{2n} + \Delta_{3n}. \end{aligned} \quad (7.32)$$

Using  $|g_t| \leq C \sum_{j=m}^\infty |\psi_j \lambda'_{t-j}| (1 + |u_{mt}|^\beta)$  again, it follows from (7.23) with  $m = 1 + \beta$  ( $\leq 2\beta$ ) that, whenever  $\nu_n \geq m$ ,

$$\begin{aligned} |\Delta_{1n}| &\leq C m_0 \sum_{t=\nu_{1n}+1}^n \mathbb{E} |g_t| K[(x_t - x)/h] \\ &\leq C m_0 \sum_{j=m}^\infty \sum_{t=\nu_{1n}+1}^n \mathbb{E} \left\{ |\psi_j \lambda'_{t-j}| (1 + |u_{mt}|^\beta) K[(x_t - x)/h] \right\} \\ &\leq C_1 h \sum_{j=m}^\infty (|\psi_{1j}| + |\psi_{2j}|) \sum_{t=\nu_{1n}+1}^n d_t^{-1} \\ &\leq C \sum_{j=m}^\infty (|\psi_{1j}| + |\psi_{2j}|) (nh/d_n) = o(nh/d_n), \end{aligned} \quad (7.33)$$

as  $n \rightarrow \infty$  first and then  $m \rightarrow \infty$ . Similarly, it follows from Lemma 7.1(ii) and (7.23) with  $m = 1 + \beta$  that

$$\begin{aligned} |\Delta_{2n}| &\leq C \sum_{t=\nu_{1n}+1}^n \sum_{s=m_0+1}^{\nu_{1n}} \mathbb{E} \left\{ |g_t| K[(x_t - x)/h] \mathbb{E}(K[(x_{t+s} - x)/h] | \mathcal{F}_t) \right\} \\ &\leq C \sum_{t=\nu_{1n}+1}^n \mathbb{E} \left\{ |g_t| K[(x_t - x)/h] \right\} \sum_{s=m_0+1}^{\nu_{1n}} h/d_s \\ &= O(1) (h\nu_n/d_{\nu_n}) (nh/d_n) = o(nh/d_n). \end{aligned} \quad (7.34)$$

As for  $\Delta_{3n}$ , by Lemma 7.1 (iii) and the conditional arguments,

$$\begin{aligned}
|\Delta_{3n}| &\leq \sum_{t-s > 2\nu_n + m_0} \mathbb{E} \left\{ |g_s K[(x_s - x)/h]| \left| \mathbb{E}[g_t K[(x_t - x)/h] \mid \mathcal{F}_s] \right| \right\} \\
&\leq C \nu_n \sum_{s=1}^n \frac{h}{d_s} \sum_{t=s+\nu_{1n}}^n \frac{h}{d_{t-s}^2} \\
&\leq C \nu_n h (1 + \log n) (nd_n/h) = o(nd_n/h),
\end{aligned} \tag{7.35}$$

due to  $h\nu_n(1+\log n) = o(nh^3/d_n)^\delta = o(1)$ . Combining (7.32)-(7.35),  $R_{n6} = o_P[(nh/d_n)^{1/2}]$  as  $n \rightarrow \infty$  first and then  $m \rightarrow \infty$ . This, together with (7.30) and (7.31), implies (7.29).

The proof of Lemma 7.2 is now complete.  $\square$

**Proof of Theorem 4.1.** We start with some preliminaries. Let  $A_l = \sum_{j=l}^\infty (|\psi_{1j}| + |\psi_{2j}|)$ , where  $l$  is chosen so large that  $A_l \leq 1$ . Due to

$$u_t = \left( \sum_{j=0}^{l-1} + \sum_{j=l}^\infty \right) \psi_j \lambda'_{t-j} = u_{l,1t} + u_{l,2t}, \quad \text{say,}$$

it follows from (3.5) that, for any  $x \in \mathbb{R}$ ,

$$|m(x, u_t) - m(x, u_{l,1t})| \leq T(x) A_l^{\delta/2} (1 + |u_{l,1t}|^\beta) (1 + A_l^{-\alpha/2} |u_{l,2t}|^\alpha). \tag{7.36}$$

By recalling (7.21) and  $A_0 = \sum_{j=0}^\infty (|\psi_{1j}| + |\psi_{2j}|) < \infty$ , we further have

$$\begin{aligned}
1 + |u_{l,1t}|^\beta &\leq 1 + \left( \sum_{j=0}^{l-1} |\psi_{1j}| |\epsilon_{t-j}| + \sum_{j=0}^l |\psi_{2j}| |\eta_{t-j}| \right)^\beta \\
&\leq 1 + C_\beta A_0^{\beta-1} \sum_{j=0}^{l-1} (|\psi_{1j}| |\epsilon_{t-j}|^\beta + |\psi_{2j}| |\eta_{t-j}|^\beta) \\
&\leq 1 + C_\beta \sum_{j=0}^{l-1} (|\psi_{1j}| + |\psi_{2j}|) \|\lambda_{t-j}\|^\beta,
\end{aligned} \tag{7.37}$$

and, by letting  $\alpha^* = \max\{\alpha, 2\}$ ,

$$\begin{aligned}
1 + A_l^{-\alpha/2} |u_{l,2t}|^\alpha &\leq 2 + A_l^{-\alpha^*/2} |u_{l,2t}|^{\alpha^*} \\
&\leq 2 + A_l^{-\alpha^*/2} \left( \sum_{j=l}^\infty |\psi_{1j}| |\epsilon_{t-j}| + \sum_{j=l}^\infty |\psi_{2j}| |\eta_{t-j}| \right)^{\alpha^*} \\
&\leq 2 + C_{\alpha^*} A_l^{2^{-1}\alpha^*-1} \sum_{j=0}^\infty (|\psi_{1j}| |\epsilon_{t-j}|^{\alpha^*} + |\psi_{2j}| |\eta_{t-j}|^{\alpha^*}) \\
&\leq 2 + C_{\alpha^*} \sum_{j=0}^\infty (|\psi_{1j}| + |\psi_{2j}|) \|\lambda_{t-j}\|^{\alpha^*},
\end{aligned} \tag{7.38}$$

where  $C_\beta$  and  $C_{\alpha^*}$  are constants depending only on  $\beta$  or  $\alpha$ , respectively.

Similarly, for any  $x, x_0 \in \mathbb{R}$ , we have

$$\begin{aligned} |m(x, u_{l,1t}) - m(x, x_0)| &\leq T(x) (1 + |x_0|^\beta) (1 + |u_{l,1t} - x_0|^\alpha) \\ &\leq C_{\alpha, x_0} T(x) \sum_{j=0}^{l-1} (|\psi_{1j}| + |\psi_{2j}|) \|\lambda_{t-j}\|^\alpha, \end{aligned} \quad (7.39)$$

where  $C_{\alpha, x_0}$  is a constant depending only on  $\alpha$  and  $x_0$ .

We are now ready to prove Theorem 4.1. First assume  $\nu_{nk} = 0$ . This restriction will be removed later. For convenience of notation, we further assume  $z = 0$ . The removal of the restriction  $z = 0$  is standard and so details are omitted.

Let  $m_{1l}(x) = \mathbb{E}m(x, u_{l,1l})$ . We may write

$$\frac{c_n}{n} \sum_{t=1}^n m(c_n Z_{nt}, u_t) = S_n + S_{1n} + S_{2n},$$

where  $S_n = \frac{c_n}{n} \sum_{t=1}^n m_{1l}(c_n Z_{nt})$ ,

$$\begin{aligned} S_{1n} &= \frac{c_n}{n} \sum_{t=1}^n \left[ m(c_n Z_{nt}, u_t) - m(c_n Z_{nt}, u_{l,1t}) \right], \\ S_{2n} &= \frac{c_n}{n} \sum_{t=1}^n \left[ m(c_n Z_{nt}, u_{l,1t}) - m_{1l}(c_n Z_{nt}) \right]. \end{aligned}$$

It follows from Corollary 2.3 (i) of Wang (2015) that, for any  $l \geq 1$ ,

$$S_n \rightarrow_d \int_{-\infty}^{\infty} m_{1l}(t) dt L_Z(1, 0).$$

Since, by (7.36)-(7.38),

$$\begin{aligned} \mathbb{E}|m(t, u_1) - m(t, u_{l,1l})| &\leq T(t) A_l^{\delta/2} \mathbb{E}(1 + |u_{l,1l}|^\beta) (1 + A_l^{-\alpha/2} |u_{l,2l}|^\alpha) \\ &\leq C T(t) A_l^{\delta/2}, \end{aligned}$$

we have  $\int_{-\infty}^{\infty} |m_{1l}(t) - m_1(t)| dt \leq C A_l^{\delta/2} \int_{-\infty}^{\infty} T(t) dt \rightarrow 0$ , i.e.,

$$\int_{-\infty}^{\infty} m_{1l}(t) dt \rightarrow \int_{-\infty}^{\infty} m_1(t) dt, \quad \text{as } l \rightarrow \infty.$$

Hence, to prove (4.8) with  $\nu_{nk} = 0$ , it suffices to show that

$$S_{in} = o_P(1), \quad i = 1, 2, \quad (7.40)$$

as  $n \rightarrow \infty$  first and then  $l \rightarrow \infty$ .

The proof of (7.40) for  $i = 1$  is simple. Indeed, due to (7.36)-(7.38) and  $\mathbb{E}||\lambda_0||^{\max\{2,\alpha,\beta\}} < \infty$ , it follows from Lemma 7.1 (i) with  $h = d_n/c_n$  and  $m = 0$  that

$$\begin{aligned}
\mathbb{E}|S_{1n}| &\leq \frac{c_n}{n} \sum_{t=1}^n \mathbb{E}|m(c_n Z_{nt}, u_t) - m(c_n Z_{nt}, u_{l,1t})| \\
&\leq A_l^{\delta/2} \frac{c_n}{n} \sum_{t=1}^n \mathbb{E}(1 + A_l^{-\alpha/2} |u_{l,2t}|^\alpha) (1 + |u_{l,1t}|^\beta) T(c_n Z_{nt}) \\
&\leq C A_l^{\delta/2} \sup_{i,j \geq 0, i \neq j} \frac{c_n}{n} \sum_{t=1}^n \mathbb{E}(1 + ||\lambda_{t-i}||^{\alpha*}) (1 + ||\lambda_{t-j}||^\beta) T(c_n Z_{nt}) \\
&\leq C A_l^{\delta/2} (1 + \frac{d_n}{n} \sum_{t=m_0}^n d_k^{-1}) \leq C A_l^{\delta/2} \rightarrow 0,
\end{aligned}$$

as  $n \rightarrow \infty$  first and then  $l \rightarrow \infty$ , which implies (7.40) with  $i = 1$ .

We next prove (7.40) with  $i = 2$ . Write  $p(x, y) = m(x, y) - m_{1l}(x)$ . First note that, by the boundedness and integrability of  $\mathbb{E}|m(x, u_1)|$ , there exists a finite constant  $x_0$  such that  $m(x, x_0)$  is bounded and integrable. For this  $x_0$ , it follows from (7.39) that, for any  $l \geq 1$  and  $x \in \mathbb{R}$ ,

$$\begin{aligned}
|p(x, u_{l,1t})| &\leq |m(x, x_0)| + C_{\alpha, x_0} |g(x)| \sum_{j=0}^{l-1} (|\psi_{1j}| + |\psi_{2j}|) (||\lambda_{t-j}||^\alpha + \mathbb{E}||\lambda_{t-j}||^\alpha) \\
&\leq C (1 + ||\lambda_{t-j}||^\alpha + \mathbb{E}||\lambda_{t-j}||^\alpha).
\end{aligned} \tag{7.41}$$

Furthermore, for any  $l \geq 1$  and  $x \in \mathbb{R}$ ,

$$\begin{aligned}
\mathbb{E}|p(x, u_{l,1l})| (1 + \sum_{j=1}^l |\epsilon_j|) &\leq C \mathbb{E}\{|m(x, u_{l,1l})| (1 + \sum_{j=1}^l |\epsilon_j|)\} \\
&\leq C [m(x, x_0) + g(x) \sum_{j=0}^{l-1} (|\psi_{1j}| + |\psi_{2j}|) E\{||\lambda_{l-j}||^\alpha (1 + \sum_{j=1}^l |\epsilon_j|)\}] \\
&\leq C_1 l [m(x, x_0) + T(x)] =: C_1 l T_1(x), \quad \text{say.}
\end{aligned} \tag{7.42}$$

It is readily seen that  $T_1(x) = m(x, x_0) + T(x)$  is bounded and integrable. Similarly, for any  $l \geq 1$  and  $x \in \mathbb{R}$ , we have

$$\begin{aligned}
\mathbb{E}|p(x, u_{l,1l})|^2 &\leq 2 \mathbb{E}|m(x, u_{l,1l})|^2 \\
&\leq C [m^2(x, x_0) + T^2(t) \sum_{j=0}^{l-1} (|\psi_{1j}| + |\psi_{2j}|) \mathbb{E}||\lambda_{l-j}||^{2\alpha}] \\
&\leq C_2 [m(x, x_0) + T(x)] = C_2 T_1(x).
\end{aligned} \tag{7.43}$$

Due to (7.41), we have

$$\mathbb{E}p^2(c_n Z_{nk}, u_{l,1k}) \leq C \tag{7.44}$$

for any  $k \geq 1$ . Due to (7.42) and (7.43), it follows from Lemma 7.1 (i) with  $h = d_n/c_n$  and  $m = l$  that

$$\begin{aligned} & \mathbb{E}(|p(c_n Z_{nk}, u_{l,1k})| + |p(c_n Z_{nk}, u_{l,1k})|^2) \\ & \leq C \frac{d_n}{c_n d_k} \int_{-\infty}^{\infty} \mathbb{E}(|p(t, u_{l,1l})| + |p(t, u_{l,1l})|^2) dt \\ & \leq C_1 \frac{d_n}{c_n d_k}, \end{aligned} \quad (7.45)$$

for any  $k \geq 2l + m_0$ . Similarly, by (7.42) and Lemma 7.1 (iii) with  $h = d_n/c_n$ , we have

$$\begin{aligned} & |\mathbb{E}[p(c_n Z_{nk}, u_{l,1k}) \mid \mathcal{F}_j]| \\ & \leq \frac{C d_n \sum_{j=0}^l |\phi_j|}{c_n d_{k-j}^2} \int_{-\infty}^{\infty} \mathbb{E}|p(t, u_{l,1l})| (1 + \sum_{j=1}^l |\epsilon_j|) dt \\ & \leq \frac{C d_n l \sum_{j=0}^l |\phi_j|}{c_n d_{k-j}^2}. \end{aligned} \quad (7.46)$$

for any  $k - j \geq 2l + m_0$ .

Result (7.40) with  $i = 2$  can now be proved by using standard conditional arguments as those of Lemma 2.2 (ii) in Wang (2015). A outline is given as follows.

For each  $l \geq 1$ , we have

$$\begin{aligned} \mathbb{E}S_{2n}^2 &= \left(\frac{c_n}{n}\right)^2 \sum_{s,t=1}^n \mathbb{E}\left\{p(c_n Z_{ns}, u_{l,1s}) p(c_n Z_{nt}, u_{l,1t})\right\} \\ &= \left(\frac{c_n}{n}\right)^2 \left( \sum_{|t-s| \leq 2l+m_0} + \sum_{|t-s| > 2l+m_0} \right) E\left\{p(c_n Z_{ns}, u_{l,1s}) p(c_n Z_{nt}, u_{l,1t})\right\} \\ &:= \Delta_{1n} + \Delta_{2n}. \end{aligned}$$

Using (7.44) and (7.45), we have

$$\begin{aligned} |\Delta_{1n}| &\leq \left(\frac{c_n}{n}\right)^2 \sum_{|t-s| \leq 2l+m_0} \mathbb{E}\left\{p^2(c_n Z_{ns}, u_{l,1s}) + p^2(c_n Z_{nt}, u_{l,1t})\right\} \\ &\leq C \left[ (l+m_0)^2 \left(\frac{c_n}{n}\right)^2 + \frac{c_n d_n}{n^2} \sum_{|t-s| \leq 2l+m_0} (d_s^{-1} + d_t^{-1}) \right] \\ &\leq C_1 \left[ \frac{(l+m_0)c_n}{n} + \left(\frac{(l+m_0)c_n}{n}\right)^2 \right]. \end{aligned}$$

Using (7.45)-(7.46) and conditioning arguments, it follows that

$$\begin{aligned} |\Delta_{2n}| &\leq 2 \left(\frac{c_n}{n}\right)^2 \sum_{t-s > 2l+m_0} \mathbb{E}\left\{|p(c_n Z_{ns}, u_{l,1s})| |\mathbb{E}[p(c_n Z_{nt}, u_{l,1t}) \mid \mathcal{F}_s]|\right\} \\ &\leq C l \sum_{j=0}^l |\phi_j| \frac{d_n^2}{n^2} \sum_{s=1}^n \frac{1}{d_s} \sum_{t=s+2l}^n \frac{1}{d_{t-s}^2} \\ &\leq C l \frac{d_n \log n}{n}. \end{aligned}$$

Combining all these estimates, it follows that

$$\begin{aligned}\mathbb{E}S_{2n}^2 &\leq \Delta_{1n} + \Delta_{2n} \\ &\leq Cl \frac{d_n \log n}{n} + C_1 \left[ \frac{(l + m_0)c_n}{n} + \left( \frac{(l + m_0)c_n}{n} \right)^2 \right] \rightarrow 0,\end{aligned}$$

as  $n \rightarrow \infty$  first and then  $l \rightarrow \infty$ , yielding (7.40) with  $i = 2$ .

The proof of (4.8) with  $\nu_{nk} = 0$  is now complete. We next remove the restriction  $\nu_{nk} = 0$ . In fact, by (3.5), we have

$$\begin{aligned}&\frac{c_n}{n} \sum_{t=1}^n m(c_n Z_{nt}, u_t + \nu_{nt}) \\ &= \frac{c_n}{n} \sum_{t=1}^n m(c_n Z_{nt}, u_t) + O(\delta_n^\delta) \frac{c_n}{n} \sum_{t=1}^n (1 + |\nu_t|^\alpha)(1 + |u_t|^\beta) T(c_n Z_{nt}), \quad (7.47)\end{aligned}$$

where  $\nu_t = \sum_{j=0}^\infty (|\varphi_{1j} \epsilon_{k-j}| + |\varphi_{2j} \eta_{k-j}|)$ . Note that

$$(1 + |\nu_t|^\alpha)(1 + |u_t|^\beta) \leq (1 + \tilde{u}_t)^{\alpha+\beta},$$

where  $\tilde{u}_t = \sum_{j=0}^\infty (\theta_{1j} |\epsilon_{k-j}| + \theta_{2j} |\eta_{k-j}|)$  with

$$\theta_{1j} = |\varphi_{1j}| + |\psi_{1j}| \text{ and } \theta_{2j} = |\varphi_{2j}| + |\psi_{2j}|. \quad (7.48)$$

As  $\delta_n \rightarrow 0$ , result (4.8) follows from that of the first part with  $\nu_{nk} = 0$  and (7.22) with  $h = d_n/c_n$ .

The proof of Theorem 4.1 is now complete.  $\square$

**Proof of Corollary 4.1.** We first prove (4.10). For any given  $x$ , write  $\kappa_{nt} = \alpha_0 x + u_t + \nu_{nt}$  and  $\tilde{\kappa}_{nt} = (\alpha_{nt} - \alpha_0)x + \kappa_{nt}$ . Since  $y_t = h\alpha_{nt}(x_t - x)/h + \tilde{\kappa}_{nt}$  and  $\tilde{\kappa}_{nt} = \beta_n(\alpha_{nt} - \alpha_0)x/\beta_n + \kappa_{nt}$ , where  $\beta_n = \max_{1 \leq k \leq n} |\alpha_{nk} - \alpha_0|$ , it follows from (3.6) that

$$\begin{aligned}|f(y_t) - f(\kappa_{nt})| &\leq |f(y_t) - f(\tilde{\kappa}_{nt})| + |f(\tilde{\kappa}_{nt}) - f(\kappa_{nt})| \\ &\leq Ch^\delta [1 + |\alpha_{nt}|^\alpha (|x_t - x|/h)^\alpha] (1 + |\tilde{\kappa}_{nt}|^\beta) \\ &\quad + C\beta_n^\delta (1 + |x|^\alpha) (1 + |\kappa_{nt}|^\beta) \\ &\leq C_{x,\alpha} (h^\delta + \beta_n^\delta) (1 + |\tilde{u}_t|^\beta) [1 + (|x_t - x|/h)^\alpha], \quad (7.49)\end{aligned}$$

where  $C_{x,\alpha}$  is a constant depending only on  $\alpha$  and  $x$ , and

$$\tilde{u}_t = \sum_{j=0}^\infty (\theta_{1j} |\epsilon_{k-j}| + \theta_{2j} |\eta_{k-j}|),$$

with  $\theta_{1j} = |\varphi_{1j}| + |\psi_{1j}|$  and  $\theta_{2j} = |\varphi_{2j}| + |\psi_{2j}|$ , as given in (7.48).



Let  $K_1(s) = (1 + |s|^\alpha)K(s)$ . It follows from (7.49) and (7.22) with  $p(s) = K_1(s)$  that

$$\begin{aligned} & \frac{d_n}{nh} \sum_{t=1}^n f(y_t) K[(x_t - x)/h] \\ &= \frac{d_n}{nh} \sum_{t=1}^n f(\kappa_{nt}) K[(x_t - x)/h] + O(h^\delta + \beta_n^\delta) \frac{d_n}{nh} \sum_{t=1}^n (1 + |\tilde{u}_t|^\beta) K_1[(x_t - x)/h] \\ &= \frac{d_n}{nh} \sum_{t=1}^n f(\kappa_{nt}) K[(x_t - x)/h] + o_P(1), \end{aligned}$$

due to  $h \rightarrow 0$  and  $\beta_n \rightarrow 0$ . Result (4.10) now follows from (4.8) with

$$m(t, y) = K(t) f(\alpha_0 x + y), \quad c_n = d_n/h, \quad c'_n = 1/d_n, \quad z = -x.$$

The proof of (4.11) is similar. Indeed, in this case we may write

$$y_t = \beta_n(\alpha_{nt} - \alpha_0)x_t/\beta_n + \alpha_0 x_t + u_t + \nu_{nt},$$

and it follows from (3.6) that

$$\begin{aligned} & |f(y_t) - f(\alpha_0 x_t + u_t + \nu_{nt})| \\ & \leq C\beta_n^\delta (1 + |x_t|^\alpha) (1 + |\alpha_0 x_t + u_t + \nu_{nt}|^\beta) \\ & \leq C_{x,\alpha}\beta_n^\delta (1 + |x_t - x|^{\alpha+\beta}) (1 + |\tilde{u}_t|^\beta), \end{aligned}$$

implying that (letting  $K_2(s) = (1 + |s|^{\alpha+\beta})K(s)$ )

$$\begin{aligned} & \frac{d_n}{nh} \sum_{t=1}^n f(y_t) K(x_t - x) \\ &= \frac{d_n}{nh} \sum_{t=1}^n f(\alpha_0 x_t + u_t + \nu_{nt}) K(x_t - x) + O(\beta_n^\delta) \frac{d_n}{nh} \sum_{t=1}^n (1 + |\tilde{u}_t|^\beta) K_2[(x_t - x)/h] \\ &= \frac{d_n}{nh} \sum_{t=1}^n f(\alpha_0 x_t + u_t + \nu_{nt}) K(x_t - x) + o_P(1). \end{aligned}$$

Result (4.11) follows from (4.8) with

$$m(t, y) = K(t) f(\alpha_0 x + \alpha_0 t + y), \quad c_n = d_n, \quad c'_n = 1/d_n, \quad z = -x.$$

The proof of Corollary 4.1 is now complete.  $\square$

**Proof of Theorem 5.1.** We may write

$$\begin{aligned} \hat{g}(x) &= \frac{\sum \eta_t K[(x_t - x)/h]}{\sum K[(x_t - x)/h]} + \frac{\sum g(y_t) K[(x_t - x)/h]}{\sum K[(x_t - x)/h]} \\ &:= R_{1n} + R_{2n}. \end{aligned} \tag{7.50}$$

As in Wang and Phillips (2016) (see, also, Lemma 7.2), it is easy to show that  $R_{1n} = O_P[(nh^2)^{1/4}]$ . On the other hand, a simple application of Corollary 4.1 yields that

$$\begin{aligned} & \left\{ \frac{d_n}{nh} \sum_{t=1}^n K[(x_t - x)/h], \frac{d_n}{nh} \sum_{t=1}^n g(y_t) K[(x_t - x)/h] \right\} \\ \rightarrow_D & \left\{ L_Z(1, 0), \mathbb{E}g(x + u_1) \times L_Z(1, 0) \right\}. \end{aligned} \quad (7.51)$$

The result (5.16) follows from the continuous mapping theorem.  $\square$

**Proof of Theorem 5.2.** We may write

$$\sum g(y_t) K[(x_t - x)/h] = y_{n1} + y_{n2},$$

where

$$\begin{aligned} y_{n1} &= \sum g(x + u_t) K[(x_t - x)/h] \\ y_{n2} &= \sum [g(\alpha_{nt}x_t + \nu_{nt} + u_t) - g(x + u_t)] K[(x_t - x)/h] \end{aligned}$$

Due to **A5** (i), (iv) and the fact that  $K(x)$  has a finite compact support, for any fixed  $x$  we have

$$\begin{aligned} |y_{n2}| &\leq C_x \sum (|\alpha_{nt}| |x_t - x| + |\alpha_{nt} - 1| + \delta_n) (1 + |u_t|^\beta) (1 + |\tilde{u}_t|) K[(x_t - x)/h] \\ &\leq C_x (h + \beta_n + \delta_n) \sum_{k=1}^n (1 + |u_k|^\beta) (1 + |\tilde{u}_t|) K[(x_t - x)/h] \\ &= O_P\left[(h + \beta_n + \delta_n) \frac{nh}{d_n}\right] = o_P\left[\left(\frac{nh}{d_n}\right)^{1/2}\right], \end{aligned}$$

where  $\tilde{u}_t = \sum_{j=0}^{\infty} (|\varphi_{1j} \epsilon_{k-j}| + |\varphi_{2j} \eta_{k-j}|)$  and we have used Hölder's inequality and (7.22). Taking these facts into (7.50), simple calculations show that (5.17) will follow if we prove

$$\begin{aligned} & \frac{d_n}{nh} \sum_{t=1}^n K[(x_t - x)/h], \left(\frac{d_n}{nh}\right)^{1/2} \sum_{t=1}^n w_t K[(x_t - x)/h] \\ \rightarrow_D & (L_Z(1, 0), \Lambda N \times L_Z(1, 0)^{1/2}), \end{aligned} \quad (7.52)$$

where  $w_t = \eta_t + g(x + u_t) - \mathbb{E}g(x + u_t)$  and  $N \sim N(0, 1)$  independent of  $L_Z(1, 0)$ . This follows from a simple application of Lemma 7.2, since  $\tilde{g}(y) = g(x + y) - \mathbb{E}g(x + u_1)$  still satisfies **A5**(i) with  $\mathbb{E}\tilde{g}(u_1) = 0$  for any fixed  $x \in \mathbb{R}$ .  $\square$

## 8 Appendix B: Proof of (7.20)

Note that

$$\begin{aligned} x_k - x_j &= \sum_{i=j+1}^k \rho_n^{k-i} \xi_i + \sum_{i=1}^j (\rho_n^{k-i} - \rho_n^{j-i}) \xi_i \\ &= \sum_{i=j+1}^k \rho_n^{k-i} \left( \sum_{u=j+1}^i + \sum_{u=-\infty}^j \right) \epsilon_u \phi_{i-u} + \sum_{i=1}^j (\rho_n^{k-i} - \rho_n^{j-i}) \xi_i. \end{aligned}$$

We may have

$$x_k = x_{1jk} + x_{2jk}, \quad (8.53)$$

where  $x_{1jk} = \sum_{i=j+1}^k \epsilon_i a_{k,i}$  with

$$a_{k,i} = \sum_{u=i}^k \rho_n^{k-u} \phi_{u-i} = a_{k-i},$$

and  $x_{2jk}$  depends only on  $\epsilon_j, \epsilon_{j-1}, \dots$

Let  $\Lambda_m = \sum_{j=1}^m \epsilon_{t_j} a_{k-t_j}$  and  $y_{jk}^* = x_{1jk} - \Lambda_m$ . It is readily seen that there exists an  $m_0 > 0$  such that, whenever  $k - j \geq 2m + m_0$ ,  $0 < a_1 \leq E(y_{jk}^*)^2 / d_{k-j}^2 \leq a_2 < \infty$ , where  $a_1$  and  $a_2$  are constants. As a consequence, similar arguments as in the proof of Theorem 2.18 of Wang (2015) [In particular, see part (ii), the fact **F**, and (2.66)] yields that, whenever  $k - j \geq 2m + m_0$ ,  $y_{jk}^* / d_{k-j}$  has a density function  $\nu_{jk}(x)$ , which is uniformly bounded over  $x$  by a constant  $C$  and

$$\sup_x |\nu_{jk}(x+u) - \nu_{jk}(x)| \leq C \min\{|u|, 1\}. \quad (8.54)$$

This, together with (8.53) and the independence of  $\epsilon_i$ , implies that

$$\begin{aligned} \mathbb{E}\{p(x_k/h, \lambda_{t_1}, \dots, \lambda_{t_m}) \mid \mathcal{F}_j\} &= \mathbb{E}\{p[(x_{2jk} + \Lambda_m + y_{jk}^*)/h, \lambda_{t_1}, \dots, \lambda_{t_m}] \mid \mathcal{F}_j\} \\ &= \mathbb{E}\left\{ \int_{-\infty}^{\infty} p[(x_{2jk} + \Lambda_m + d_{k-j}y)/h, \lambda_{t_1}, \dots, \lambda_{t_m}] \nu_{jk}(y) dy \mid \mathcal{F}_j \right\} \\ &= \frac{h}{d_{k-j}} \int_{-\infty}^{\infty} \mathbb{E}\left\{ p(y, \lambda_{t_1}, \dots, \lambda_{t_m}) \nu_{jk}\left(\frac{-x_{2jk} - \Lambda_m + hy}{d_{k-j}}\right) \mid \mathcal{F}_j \right\} dy. \end{aligned} \quad (8.55)$$

As  $x_{2jk}$  depends only on  $\epsilon_j, \epsilon_{j-1}, \dots$ , and  $j+1 \leq t_1, \dots, t_m \leq k$ , we have

$$\begin{aligned} &\mathbb{E}\left\{ p(y, \lambda_{t_1}, \dots, \lambda_{t_m}) \nu_{jk}\left(\frac{-x_{2jk} + hy}{d_{k-j}}\right) \mid \mathcal{F}_j \right\} \\ &= \nu_{jk}\left(\frac{-x_{2jk} + hy}{d_{k-j}}\right) \mathbb{E}\{p(y, \lambda_{t_1}, \dots, \lambda_{t_m})\} = 0. \end{aligned}$$

Taking this fact into (8.55) and using (8.54), we have

$$\begin{aligned}
& |\mathbb{E}\{p(x_k/h, \lambda_{t_1}, \dots, \lambda_{t_m}) \mid \mathcal{F}_j\}| \\
& \leq \frac{h}{d_{k-j}} \int_{-\infty}^{\infty} \mathbb{E}\left\{p(y, \lambda_{t_1}, \dots, \lambda_{t_m}) \right. \\
& \quad \left. \left| \nu_{jk}\left(\frac{-x_{2jk} - \Lambda_m + hy}{d_{k-j}}\right) - \nu_{jk}\left(\frac{-x_{2jk} + hy}{d_{k-j}}\right) \right| \mid \mathcal{F}_j\right\} dy \\
& \leq \frac{Ch}{d_{k-j}} \int_{-\infty}^{\infty} \mathbb{E}\left\{|p(y, \lambda_{t_1}, \dots, \lambda_{t_m})| \min\{|\Lambda_m|/d_{k-j}, 1\}\right\} dy \\
& \leq \frac{Ch \sum_{j=0}^{k-\min\{t_1, \dots, t_m\}} |\phi_j|}{d_{k-j}^2} \int_{-\infty}^{\infty} \mathbb{E}\left\{|p(y, \lambda_1, \dots, \lambda_m)| \sum_{j=1}^m |\epsilon_j|\right\} dy,
\end{aligned}$$

as required.  $\square$

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